

Streaming Ranked-Tree-to-String Transducers

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Abstract. *Streaming tree transducers with single-use restriction* (STT_{surS}) were introduced by Alur and D’Antoni as an analyzable, executable, and expressive model for transforming unranked ordered trees in a single pass. The equivalence problem of STT_{surS} is decidable because their class is as expressive as the class of MSO-definable tree transformations. In this paper, we present *streaming ranked-tree-to-string transducers* (SRTSTs), based on STT_{surS} : SRTSTs are released from the single-use restriction while their input and output are restricted to ranked trees and strings, respectively. We show that the expressiveness of SRTSTs coincides with that of *deterministic top-down tree transducers with regular look-ahead* (yDT^{R} s), whose equivalence problem is known to be decidable. Our proof is done by constructing equivalent transducers in both directions.

Keywords: ranked trees · streaming transducers · expressiveness · equivalence.

1 Introduction

Streaming tree transducers with single-use restriction (STT_{surS}) were introduced in [1] which can characterize MSO-definable tree transformations in a single path. An STT_{sur} defines a function over unranked ordered trees (and forests), which are encoded as *nested words*. A nested word is a string over symbols tagged with *open/close* brackets. An STT_{sur} reads an input nested word from left to right in a single path. Here each state is equipped with a *visibly pushdown stack* and a finite number of *variables* that store output chunks. An STT_{sur} updates variables and a stack that stores *stack symbols* along with updated values of variables.

Intuitively, the single-use restriction is a restriction that variables are updated in a manner that ensures that each value of a variable contributes *at most once* to the eventual output without duplication (see [1] for the definition). Due to this restriction, the class of STT_{surS} equals that of MSO-definable tree transducers.

The equivalence problem of transducers is an important topic in formal language theory. One of the remarkable results is that the equivalence of MSO-definable tree transducers is decidable [8]. Furthermore, in [1] the decidability of the equivalence problem for STT_{surS} was proved without using the result for MSO-definable transducers, with better complexity.

In this paper, we propose *streaming ranked-tree-to-string transducers* (SRTSTs) as a model of transformations from ranked trees to strings. The definition of

SRTSTs is based on that of STT_{sur} s but released from the single-use restriction. In addition, the input and output of SRTSTs are restricted to ranked trees and strings, respectively, while those of STT_{sur} s are both unranked trees. SRTSTs with single-use restriction ($\text{SRTST}_{\text{sur,s}}$) (which are nothing but $\text{STST}_{\text{sur,s}}$ [1] whose input is restricted to ranked trees) have the same expressive power as MSO-definable ranked-tree-to-string transducers (see Appendix A); and SRTSTs are more expressive than $\text{SRTST}_{\text{sur,s}}$. Streaming transducers without single-use restriction were not studied in [1].³

Deterministic top-down tree-to-string transducers with regular look-ahead (yDT^{R} s) [5] are a classical model for structural-recursive tree-to-string transformation. A yDT^{R} defines a transformation from ranked trees to strings by mutually recursive functions with regular look-ahead. The equivalence of yDT^{R} s had been a long-standing open problem [6], that was recently solved by Seidl et al. [12,13] and their decision procedure was implemented and experimented in [15]. For a subclass of yDT^{R} , the notion of *finite copying* for top-down tree transducers was introduced in [9]. Intuitively, a yDT^{R} is finite copying ($\text{yDT}_{\text{fc}}^{\text{R}}$), if each subtree of an input is copied at most a bounded number of times. The expressiveness of $\text{yDT}_{\text{fc}}^{\text{R}}$ s coincides with that of MSO-definable tree-to-string transducers [7], thereby $\text{yDT}_{\text{fc}}^{\text{R}}$ and $\text{SRTST}_{\text{sur}}$ are equi-expressive.

In this paper, we characterize the class of SRTSTs in terms of yDT^{R} s. Our contributions are:

- (i) SRTSTs and yDT^{R} s are equi-expressive,
- (ii) bottom-up SRTSTs and SRTSTs are equi-expressive, and
- (iii) the equivalence problem for SRTSTs is decidable.

Our main contribution is (i). In Section 4, we show how to construct equivalent transducers for each direction. In the direction from yDT^{R} s to SRTSTs, we construct the equivalent SRTST to be bottom-up one for every given yDT^{R} , which shows (ii). As an immediate corollary, (iii) is derived from (i) and the decidability of the equivalence problem for yDT^{R} s [13].

Related work There is a subclass of yDT^{R} s besides $\text{yDT}_{\text{fc}}^{\text{R}}$ s, called yDT_{seq} s, which are restricted to non-copying and order-preserving on input variables occurring in right-hand sides of rules. yDT_{seq} s are equi-expressive to *deterministic nested word-to-word transducers* [14], which is a subclass of $\text{SRTST}_{\text{sur,s}}$ hence their equivalence problem is known to be decidable.

As for streaming string-to-string transducers rather than tree-to-string ones, *copyless streaming string transducers* (SST_{cls}) have been introduced in [3]. The expressiveness of SST_{cls} coincides with that of MSO-definable string transducers. *Copyful streaming string transducers* (SST_{cfs}) that are released from the copyless restriction are studied in [10]. It is shown that SST_{cfs} and HDTOL systems are equi-expressive.

³ In the current paper, notions with (resp. without) single-use restriction are written by words with (resp. without) the subscript sur such as STT_{sur} (resp. STT). In [1], STT_{sur} and STST_{sur} are written just as STT and STST , respectively.

Macro forest transducers that are richer than yDT^{R} s have been translated into streaming transducers to obtain efficient XML stream processors [11]. The streaming model is rather informal and its expressiveness has not been studied.

2 Preliminaries

For $n \in \mathbb{N}$, we write $[n]$ for the set $\{1, \dots, n\}$; in particular, $[0] = \emptyset$. We use boldface letters such as \mathbf{t} to denote tuples. For a k -tuple \mathbf{t} , we write $|\mathbf{t}|$ for the length k of \mathbf{t} . For a set A and $k \in \mathbb{N}$, A^k denotes the set of all k -tuples of elements of A , and $A^{(\leq k)} \triangleq \bigcup_{i=0}^k A^i$. For $\mathbf{t} = (a_1, \dots, a_k) \in A^k$ and $a \in A$, we denote by $\mathbf{t} \parallel a$ the $(k+1)$ -tuple (a_1, \dots, a_k, a) . We write ε for the empty string, and $\text{Dom}(f)$ for the domain of definition of a partial function f .

A *ranked alphabet* is a pair of a finite set Σ and a function $\text{rank}_{\Sigma} : \Sigma \rightarrow \mathbb{N}$; the value $\text{rank}_{\Sigma}(\sigma)$ of a symbol σ is called the *rank* of σ . We define $\Sigma^{(n)} \triangleq \{\sigma \in \Sigma \mid \text{rank}_{\Sigma}(\sigma) = n\}$, and write σ also as $\sigma^{(n)}$ when $\sigma \in \Sigma^{(n)}$. The set of (*ranked*) *trees over Σ* , denoted by \mathcal{T}_{Σ} , is the smallest set T such that if $\sigma \in \Sigma^{(n)}$ and $t_1, \dots, t_n \in T$ then $\sigma(t_1, \dots, t_n) \in T$. We use an English letter (mainly e) as a metavariable ranging over rank-0 letters, i.e., leaves; a tree of the form $e()$ is written as e .

An *alphabet* is just a finite set. Let Σ be an alphabet. A *tagged alphabet* $\hat{\Sigma}$ consists of the *call symbols* $\langle \sigma$, and the *return symbols* $\sigma \rangle$, for all $\sigma \in \Sigma$. A *nested word* over Σ is a finite sequence over $\hat{\Sigma}$. We simply write $\langle e \rangle$ for a nested word of the form $\langle e e \rangle$. A nested word w is called *well-matched* if all the left and right angle brackets occurring in w are well-bracketed; and w is called *well-labeled* if each matched pair of call and return symbols is labeled with the same symbol in Σ . Any well-labeled nested word is well-matched. For example, $\langle \mathbf{a} \mathbf{b} \rangle \langle \mathbf{a} \mathbf{b} \rangle$ is well-matched but not well-labeled; $\langle \mathbf{a} \mathbf{a} \rangle \langle \mathbf{b} \langle \mathbf{a} \mathbf{a} \rangle \mathbf{b} \rangle$ is well-labeled; and $\langle \mathbf{a} \mathbf{a} \rangle \langle \mathbf{b} \langle \mathbf{b} \rangle$ is not well-matched.

Let Σ be a ranked alphabet. A mapping from ranked trees to nested words $[-] : \mathcal{T}_{\Sigma} \rightarrow \hat{\Sigma}^*$ is defined by $[t] = \langle \sigma [t_1] \cdots [t_n] \sigma \rangle$ for $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_{\Sigma}$. The set of *ranked nested words*, denoted by $[\mathcal{T}_{\Sigma}]$, is defined by $\{[t] \mid t \in \mathcal{T}_{\Sigma}\}$. Ranked nested words respect ranks but well-labeled nested words do not necessarily (furthermore, well-labeled nested words can express not just unranked trees but even forests). For example, for $\sigma^{(2)} \in \Sigma$, $\langle \sigma \sigma \rangle$ is well-labeled, but is not a ranked nested word as $\sigma()$ is not a ranked tree. Note that $[-]$ is injective, and $[\mathcal{T}_{\Sigma}]$ is isomorphic to \mathcal{T}_{Σ} ; we write the converse function from ranked nested words to ranked trees as $[-] : [\mathcal{T}_{\Sigma}] \rightarrow \mathcal{T}_{\Sigma}$. In this paper, we are interested in ranked nested words rather than well-labeled nested words.

Definition 1. A *non-deterministic finite state bottom-up tree automaton (NBTA)* is a tuple (Π, Σ, θ) where:

- Π is a finite set of *states*,
- Σ is a ranked alphabet of *input symbols*, and
- $\theta : \bigcup_{n \in \mathbb{N}} (\Sigma^{(n)} \times \Pi^n) \rightarrow 2^{\Pi}$ is a function called a *transition function*.

Let $A = (\Pi, \Sigma, \theta)$ be an NBTA. We extend θ to $\hat{\theta} : \mathcal{T}_\Sigma \rightarrow 2^\Pi$ by induction: $\hat{\theta}(\sigma(t_1, \dots, t_n)) \triangleq \bigcup_{\pi_1 \in \hat{\theta}(t_1), \dots, \pi_n \in \hat{\theta}(t_n)} \theta(\sigma, (\pi_1, \dots, \pi_n))$. We say that a state $\pi \in \Pi$ *accepts* a tree $t \in \mathcal{T}_\Sigma$ if $\pi \in \hat{\theta}(t)$. We denote by $\mathcal{L}_A(\pi)$ the set of trees accepted by π ; we simply write $\mathcal{L}(\pi)$ for $\mathcal{L}_A(\pi)$ when A is clear from the context. We assume that $\mathcal{L}_A(\pi) \neq \emptyset$ for all $\pi \in \Pi$. An NBTA A is called a *deterministic finite state bottom-up tree automaton* (DBTA) if $\theta(\sigma, (\pi_1, \dots, \pi_n))$ has exactly one element for every $\sigma \in \Sigma^{(n)}$ and $\pi_1, \dots, \pi_n \in \Pi$. For a DBTA, we write $\theta(\sigma, (\pi_1, \dots, \pi_n))$ for its unique element. DBTAs and NBTAs recognize the same class of tree languages known as *regular tree languages* [4]. We denote by REG the set of all regular tree languages. REG is closed under union, intersection, and complementation.

3 Transducers

We here define the two main notions to be compared: yDT^R and SRTST.

3.1 Deterministic Top-Down Tree-to-String Transducers with Regular Look-ahead

A deterministic top-down tree-to-string transducer with regular look-ahead (yDT^R for short) works on ranked trees.

First we prepare the range of the right hand sides of transition rules of yDT^R s. We fix a set of input variables $X = \{x_1, x_2, \dots\}$ and define $X_n \triangleq \{x_1, \dots, x_n\}$ for $n \in \mathbb{N}$. Also, for a set Q and $n \in \mathbb{N}$, we define $Q(X_n) \triangleq \{q(x_i) \mid q \in Q, i \leq n\}$ where $q(x_i) \triangleq (q, x_i)$. For a finite set Q (of *states*), an alphabet Δ , and $n \in \mathbb{N}$, we define the set $Rhs_{Q, \Delta}(X_n)$ of *expressions* by $\tau ::= \varepsilon \mid a\tau \mid q(x_i)\tau$ where $a \in \Delta$ and $q(x_i) \in Q(X_n)$. The following definition of yDT^R is taken from [13], except that we adopt the style in [5] for regular look-ahead (i.e., we consider directly regular tree languages rather than states of an NBTA).

Definition 2 (yDT^R). A *deterministic top-down tree-to-string transducer with regular look-ahead* (yDT^R) is a tuple $(Q, \Sigma, \Delta, Init, R)$ satisfying the following conditions:

- Q is a finite set of *states*.
- Σ is a ranked alphabet of *input symbols*.
- Δ is an alphabet of *output symbols*.
- $Init \subseteq Rhs_{Q, \Delta}(X_1) \times (REG \setminus \{\emptyset\})$ is a finite set of *initial sequences*, and must satisfy that, for any two distinct initial sequences (τ, L) and (τ', L') in $Init$, $L \cap L' = \emptyset$. For $L \in REG \setminus \{\emptyset\}$, τ such that $(\tau, L) \in Init$ is unique (if it exists), and is denoted by $Init(L)$.
- $R \subseteq \bigcup_{n \in \mathbb{N}} (Q \times \Sigma^{(n)} \times Rhs_{Q, \Delta}(X_n) \times (REG \setminus \{\emptyset\})^n)$ is a finite set of *rules*, and must satisfy that, for any two distinct rules $(q, \sigma, \tau, (L_1, \dots, L_n))$ and $(q, \sigma, \tau', (L'_1, \dots, L'_n))$ in R , $L_i \cap L'_i = \emptyset$ for some $i \in [n]$. A rule $(q, \sigma, \tau, (L_1, \dots, L_n))$ is written as

$$q(\sigma(x_1, \dots, x_n)) \rightarrow \tau \quad \langle L_1, \dots, L_n \rangle .$$

Here τ is uniquely determined (if it exists) from $(q, \sigma, (L_1, \dots, L_n))$; hence we call this rule a $(q, \sigma, (L_1, \dots, L_n))$ -rule, and denote τ by $\text{rhs}(q, \sigma, (L_1, \dots, L_n))$. We write $q(e) \rightarrow \tau$ for $q(e()) \rightarrow \tau \langle \rangle$ when $\text{rank}_\Sigma(e) = 0$.

We define the semantics of a yDT^R , which transforms a tree in a top-down manner. Let $M = (Q, \Sigma, \Delta, \text{Init}, R)$ be a yDT^R , and we define a partial function $\llbracket M \rrbracket : \mathcal{T}_\Sigma \rightarrow \Delta^*$.

First, we define auxiliary partial functions $\llbracket q \rrbracket_M : \mathcal{T}_\Sigma \rightarrow \Delta^*$ (for $q \in Q$) and $\llbracket \tau \rrbracket_M : \mathcal{T}_\Sigma^n \rightarrow \Delta^*$ (for $n \in \mathbb{N}$ and $\tau \in \text{Rhs}_{Q, \Delta}(X_n)$), by simultaneous induction on input trees. Let $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$ and $q \in Q$. If there exist L_1, \dots, L_n and a $(q, \sigma, (L_1, \dots, L_n))$ -rule in R such that $t_i \in L_i$ for all $i \in [n]$, then $\llbracket q \rrbracket_M(t)$ is defined as

$$\llbracket q \rrbracket_M(\sigma(t_1, \dots, t_n)) \triangleq \llbracket \text{rhs}(q, \sigma, (L_1, \dots, L_n)) \rrbracket_M(t_1, \dots, t_n)$$

(if the r.h.s. is defined), and $\llbracket q \rrbracket_M(t)$ is not defined otherwise. Here note that, due to the condition on R , the tuple (L_1, \dots, L_n) above is unique if exists. For $n \in \mathbb{N}$ and $\tau \in \text{Rhs}_{Q, \Delta}(X_n)$, $\llbracket \tau \rrbracket_M(t_1, \dots, t_n)$ is defined as follows:

$$\begin{aligned} \llbracket \varepsilon \rrbracket_M(t_1, \dots, t_n) &\triangleq \varepsilon \\ \llbracket a\tau' \rrbracket_M(t_1, \dots, t_n) &\triangleq a \llbracket \tau' \rrbracket_M(t_1, \dots, t_n) \\ \llbracket q'(x_i)\tau' \rrbracket_M(t_1, \dots, t_n) &\triangleq \llbracket q' \rrbracket_M(t_i) \llbracket \tau' \rrbracket_M(t_1, \dots, t_n) . \end{aligned}$$

Now let us define $\llbracket M \rrbracket : \mathcal{T}_\Sigma \rightarrow \Delta^*$. For $t \in \mathcal{T}_\Sigma$, if there exists a pair $(\tau, L) \in \text{Init}$ such that $t \in L$ and if $\llbracket \tau \rrbracket_M(t)$ is defined, then we define $\llbracket M \rrbracket(t) \triangleq \llbracket \tau \rrbracket_M(t)$; and $\llbracket M \rrbracket(t)$ is not defined otherwise. Again, note that such a pair (τ, L) is unique. We denote by $\text{Dom}(M)$ the domain of $\llbracket M \rrbracket$.

In the above definition, regular look-ahead is realized by regular tree languages directly. As a finite representation for expressing regular tree languages, we use an NBTA or a DBTA, switching the two styles conveniently. (Recall that the two notions recognize the same class of languages, *REG*.) We call an automaton used for regular look-ahead a *regular look-ahead automaton*. Given a regular look-ahead automaton, we use states of the automaton instead of regular tree languages when we refer to initial sequences or rules (e.g., we write $\text{rhs}(q, \sigma, (\pi_1, \dots, \pi_n))$ for $\text{rhs}(q, \sigma, (\mathcal{L}(\pi_1), \dots, \mathcal{L}(\pi_n)))$).

The equivalence problem for yDT^R is known to be decidable.

Theorem 3 (Corollary 8.1 in [13]). *Given two yDT^R s M_1, M_2 , it is decidable whether $\llbracket M_1 \rrbracket = \llbracket M_2 \rrbracket$.*

See Appendix D for an example of a yDT^R (Example 28).

3.2 Streaming Ranked-Tree-to-String Transducers

A streaming ranked-tree-to-string transducer (SRTST for short) works on ranked nested words. We first prepare some auxiliary definitions.

For a finite set Γ (of *variables*) and an alphabet Δ , the set $E(\Gamma, \Delta)$ of *expressions over Γ and Δ* is defined by the following grammar: $E ::= \varepsilon \mid aE \mid \gamma E$ where $a \in \Delta$ and $\gamma \in \Gamma$. Note that $E(\emptyset, \Delta) = \Delta^*$.

Let Γ and Γ' be finite sets and Δ be an alphabet. We call a mapping $\rho : \Gamma \rightarrow E(\Gamma', \Delta)$ an *assignment*, and denote ρ by $[\gamma_1 := e_1, \dots, \gamma_n := e_n]$ where $\Gamma = \{\gamma_1, \dots, \gamma_n\}$ and $e_i = \rho(\gamma_i)$; in this notation, $\gamma_i := e_i$ may be omitted if $e_i = \gamma_i$. An assignment ρ is naturally extended to $\rho : E(\Gamma, \Delta) \rightarrow E(\Gamma', \Delta)$: for $e \in E(\Gamma, \Delta)$, $\rho(e)$ is the expression over Γ' and Δ obtained by replacing all occurrences of every variable γ in e with $\rho(\gamma)$. We denote $\rho(e)$ by $e\rho$. The set of all assignments over Γ , Γ' and Δ is denoted by $\mathcal{A}(\Gamma, \Gamma', \Delta)$. An element of $\mathcal{A}(\Gamma, \emptyset, \Delta)$ (i.e., a function $\Gamma \rightarrow \Delta^*$) is called an *evaluation function*, and a returned value of an evaluation function is called a *variable value*.

Given two assignments $\rho_1 : \Gamma_1 \rightarrow E(\Gamma'_1, \Delta)$ and $\rho_2 : \Gamma_2 \rightarrow E(\Gamma'_2, \Delta)$, the assignment $\rho_1\rho_2 : \Gamma_1 \rightarrow E((\Gamma'_1 \setminus \Gamma_2) \cup \Gamma'_2, \Delta)$ is defined (as usual) as follows. For $\gamma \in \Gamma_1$, $(\rho_1\rho_2)(\gamma)$ is an expression in $E((\Gamma'_1 \setminus \Gamma_2) \cup \Gamma'_2, \Delta)$ obtained by replacing all occurrences of variable $\gamma'_1 \in \Gamma'_1 \cap \Gamma_2$ in $\rho_1(\gamma) \in E(\Gamma'_1, \Delta)$ with $\rho_2(\gamma'_1) \in E(\Gamma'_2, \Delta)$, and keeping all occurrences of other variable $\gamma'_1 \in \Gamma'_1 \setminus \Gamma_2$ in $\rho_1(\gamma) \in E(\Gamma'_1, \Delta)$. Given two assignments $\rho_1 : \Gamma_1 \rightarrow E(\Gamma, \Delta)$ and $\rho_2 : \Gamma_2 \rightarrow E(\Gamma, \Delta)$ where Γ_1 and Γ_2 are disjoint, the assignment $\rho_1 \uplus \rho_2 : \Gamma_1 \uplus \Gamma_2 \rightarrow E(\Gamma, \Delta)$ is defined by

$$\rho_1 \uplus \rho_2 \triangleq [\gamma_1 := \rho_1(\gamma_1), \dots, \gamma_n := \rho_1(\gamma_n), \gamma'_1 := \rho_2(\gamma'_1), \dots, \gamma'_m := \rho_2(\gamma'_m)]$$

where $\Gamma_1 = \{\gamma_1, \dots, \gamma_n\}$ and $\Gamma_2 = \{\gamma'_1, \dots, \gamma'_m\}$.

We introduce the notion of an SRTST based on the definition of STT_{sur} in [1]. The difference is as follows: an STT_{sur} is restricted by *single-use restriction* (sur for short), while an SRTST is not restricted; the input and output of an STT_{sur} are well-matched nested words, while the input and output of an SRTST are ranked nested words and strings, respectively.

Definition 4. A *streaming ranked-tree-to-string transducer* (SRTST for short) is a tuple $(S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ where:

- S is a finite set of *states*,
- Σ is a ranked alphabet of *input symbols*,
- Δ is an alphabet of *output symbols*,
- P is a finite set of *stack symbols*,
- $s_0 \in S$ is an *initial state*,
- Γ is a finite set of *variables*,
- $F : S \rightarrow E(\Gamma, \Delta)$ is a partial function called an *output function*,
- $\delta_c : S \times \Sigma \rightarrow S \times P$ is a *call state-transition function*,
- $\delta_r : S \times P \times \Sigma \rightarrow S$ is a *return state-transition function*,
- $\rho_c : S \times \Sigma \rightarrow \mathcal{A}(\Gamma, \Gamma, \Delta)$ is a *call variable-update function*,
- $\rho_r : S \times P \times \Sigma \rightarrow \mathcal{A}(\Gamma, \Gamma \uplus \bar{\Gamma}, \Delta)$ is a *return variable-update function* where $\bar{\Gamma}$ is a “copy” of Γ , i.e., $\bar{\Gamma} \triangleq \{\bar{\gamma} \mid \gamma \in \Gamma\}$ and each $\bar{\gamma}$ is a fresh symbol.

We define the semantics of an SRTST, which transforms a tree (a ranked nested word) in a top-down and bottom-up way. Let $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$

be an SRTST. We define the set of *configurations* of T , denoted by Ψ , as $\Psi := S \times (P \times \mathcal{A}(\Gamma, \emptyset, \Delta))^* \times \mathcal{A}(\Gamma, \emptyset, \Delta)$. For a configuration $(s, \Lambda, \alpha) \in \Psi$, Λ is called the *stack*, and α is called the *current evaluation function*. Let $\alpha_\varepsilon^\Gamma \triangleq [\gamma := \varepsilon]_{\gamma \in \Gamma}$, which is called the *emptyword evaluation function*; we often omit the superscript Γ of $\alpha_\varepsilon^\Gamma$. We call $(s_0, \varepsilon, \alpha_\varepsilon^\Gamma)$ the *initial configuration*. We define the *transition function* $\delta : \Psi \times \hat{\Sigma} \rightarrow \Psi$ over configurations as follows:

Call transitions For $\sigma \in \Sigma$, $\delta((s, \Lambda, \alpha), \langle \sigma \rangle) \triangleq (s', (p, \alpha')\Lambda, \alpha_\varepsilon^\Gamma)$ where:

- $(s', p) \triangleq \delta_c(s, \sigma)$: we invoke the state-transition function δ_c , which reads $\langle \sigma \rangle$ in the state s ,
- $\alpha' \triangleq \rho_c(s, \sigma)\alpha$: we push (p, α') on the stack Λ (rather than setting α' as the current evaluation function); α' is almost $\rho_c(s, \sigma)$ but each variable γ in $\rho_c(s, \sigma)$ is substituted for $\alpha(\gamma)$ (and $\alpha(\gamma)$ is discarded if γ does not occur in $\rho_c(s, \sigma)$),
- we reset the current evaluation function α to the emptyword evaluation function $\alpha_\varepsilon^\Gamma$.

Return transitions For $\sigma \in \Sigma$, $\delta((s, (p, \beta)\Lambda, \alpha), \langle \sigma \rangle) \triangleq (s', \Lambda, \alpha')$ where:

- $s' \triangleq \delta_r(s, p, \sigma)$: we invoke the state-transition function δ_r , which read $\langle \sigma \rangle$ in the state s with the stack symbol p on the stack,
- we pop (p, β) from the stack,
- $\alpha' \triangleq \rho_r(s, p, \sigma)(\alpha \uplus \bar{\beta})$ where $\bar{\beta}$ is the “copy” of β : i.e., $\bar{\beta} \triangleq [\bar{\gamma} := \beta(\gamma)]_{\gamma \in \Gamma}$: we replace α with α' , which is almost $\rho_r(s, p, \sigma)$ but each variable γ in $\rho_r(s, p, \sigma)$ is substituted for $\alpha(\gamma)$ and each variable $\bar{\gamma}$ in $\rho_r(s, p, \sigma)$ is substituted for $\beta(\gamma)$ (and $\alpha(\gamma) / \beta(\gamma)$ is discarded if $\gamma / \bar{\gamma}$ does not occur in $\rho_c(s, \sigma)$).

Now we define the meaning $\llbracket T \rrbracket : [\mathcal{T}_\Sigma] \rightarrow \Delta^*$. First, the transition function $\delta : \Psi \times \hat{\Sigma} \rightarrow \Psi$ naturally extends to $\delta^* : \Psi \times \hat{\Sigma}^* \rightarrow \Psi$ by iterating δ . For a nested word $w \in \hat{\Sigma}^*$, we denote by $c \xrightarrow{w}_T c'$ if $\delta^*(c, w) = c'$; we omit the subscript T if it is clear from the context. Note that for any configuration c and any well-matched nested word w , $\delta^*(c, w)$ is always defined. For a ranked nested word $w \in [\mathcal{T}_\Sigma]$, if $(s_0, \varepsilon, \alpha_\varepsilon^\Gamma) \xrightarrow{w} (s, \varepsilon, \alpha)$ and if $F(s)$ is defined then $\llbracket T \rrbracket(w) \triangleq F(s)\alpha$; otherwise $\llbracket T \rrbracket(w)$ is undefined. We denote by $\text{Dom}(T)$ the domain of $\llbracket T \rrbracket$.

Example 5. We give an SRTST T : let $S \triangleq \{s_?, s_a, s_b\}$; $\Sigma \triangleq \{\mathbf{f}^{(2)}, \mathbf{a}^{(0)}, \mathbf{b}^{(0)}\}$; $\Delta \triangleq \{\mathbf{a}, \mathbf{b}\}$; $P \triangleq \{p_?, p_a, p_b\}$; $s_0 \triangleq s_?$; $\Gamma \triangleq \{\gamma\}$; $F(s) \triangleq \gamma$ for every $s \in S$; $\delta_c(s_d, \sigma) \triangleq (s_?, p_d)$ for every $\sigma \in \Sigma$ and $d \in \{\mathbf{a}, \mathbf{b}, ?\}$; δ_r is defined by

$$\delta_r(s, p_d, \sigma) \triangleq s_d, \quad \delta_r(s_d, p_?, \sigma) \triangleq s_d, \quad \delta_r(s_?, p_?, \mathbf{f}) \triangleq s_?, \quad \delta_r(s_?, p_?, d) \triangleq s_d,$$

for every $s \in S$, $\sigma \in \Sigma$, $d \in \{\mathbf{a}, \mathbf{b}\}$; ρ_c is defined by

$$\rho_c(s, \mathbf{f}) \triangleq [\gamma := \gamma], \quad \rho_c(s_?, d) \triangleq [\gamma := d], \quad \rho_c(s_a, d) \triangleq [\gamma := \gamma d], \quad \rho_c(s_b, d) \triangleq [\gamma := d\gamma],$$

for every $s \in S$ and $d \in \{\mathbf{a}, \mathbf{b}\}$; and ρ_r is defined by

$$\begin{aligned} \rho_r(s, p_?, \mathbf{f}) &\triangleq [\gamma := \gamma], & \rho_r(s, p_a, \mathbf{f}) &\triangleq [\gamma := \bar{\gamma}\gamma], & \rho_r(s, p, \mathbf{a}) &\triangleq [\gamma := \bar{\gamma}], \\ \rho_r(s, p_b, \mathbf{f}) &\triangleq [\gamma := \gamma\bar{\gamma}], & \rho_r(s, p, \mathbf{b}) &\triangleq [\gamma := \bar{\gamma}], \end{aligned}$$

for every $s \in S$ and $p \in P$. Given $t \in \mathcal{T}_\Sigma$, $\llbracket T \rrbracket(\llbracket t \rrbracket)$ recursively swaps the two subtrees of the root if the leftmost leaf is \mathbf{b} , and skip the swapping otherwise; and then produces the leaves as the output. For instance, $\llbracket T \rrbracket$ transforms $\llbracket \mathbf{f}(\mathbf{f}(\mathbf{b}, \mathbf{a}), \mathbf{f}(\mathbf{a}, \mathbf{b})) \rrbracket$ as in Fig. 1, where for clarity we denote stacks with $\llbracket - \rrbracket$.

$$\begin{array}{l}
(s?, \llbracket \cdot \rrbracket, \alpha_\varepsilon) \\
\begin{array}{l} \xrightarrow{\langle f \rangle} \\ \xrightarrow{\langle f \rangle} \\ \xrightarrow{\langle b \rangle} \\ \xrightarrow{\langle b \rangle} \\ \xrightarrow{\langle a \rangle} \\ \xrightarrow{\langle a \rangle} \\ \xrightarrow{\langle f \rangle} \end{array}
\end{array}
\left(
\begin{array}{l}
(s?, \llbracket (p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s?, \llbracket (p?, \alpha_\varepsilon)(p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s?, \llbracket (p?, [\gamma := \mathbf{b}]) (p?, \alpha_\varepsilon)(p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s_{\mathbf{b}}, \llbracket (p?, \alpha_\varepsilon)(p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{b}]) \\
(s?, \llbracket (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon)(p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s_{\mathbf{b}}, \llbracket (p?, \alpha_\varepsilon)(p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{ab}]) \\
(s_{\mathbf{b}}, \llbracket (p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{ab}])
\end{array}
\right)
\left|
\begin{array}{l}
\begin{array}{l} \xrightarrow{\langle f \rangle} \\ \xrightarrow{\langle a \rangle} \\ \xrightarrow{\langle a \rangle} \\ \xrightarrow{\langle b \rangle} \\ \xrightarrow{\langle a \rangle} \\ \xrightarrow{\langle f \rangle} \\ \xrightarrow{\langle f \rangle} \end{array}
\end{array}
\left(
\begin{array}{l}
(s?, \llbracket (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s?, \llbracket (p?, [\gamma := \mathbf{a}]) (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s_{\mathbf{a}}, \llbracket (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{a}]) \\
(s?, \llbracket (p_{\mathbf{a}}, [\gamma := \mathbf{ab}]) (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon) \rrbracket, \alpha_\varepsilon) \\
(s_{\mathbf{a}}, \llbracket (p_{\mathbf{b}}, [\gamma := \mathbf{ab}]) (p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{ab}]) \\
(s_{\mathbf{b}}, \llbracket (p?, \alpha_\varepsilon) \rrbracket, [\gamma := \mathbf{abab}]) \\
(s_{\mathbf{b}}, \llbracket \cdot \rrbracket, [\gamma := \mathbf{abab}])
\end{array}
\right)$$

Fig. 1. Transitions for $\lfloor \mathbf{f}(\mathbf{f}(\mathbf{b}, \mathbf{a}), \mathbf{f}(\mathbf{a}, \mathbf{b})) \rfloor$

4 SRTST and $\mathbf{yDT}^{\mathbf{R}}$ are equi-expressive

We show the equi-expressiveness between SRTSTs and $\mathbf{yDT}^{\mathbf{R}}$ s, by giving effective constructions in the both directions. Then (only) the construction of a $\mathbf{yDT}^{\mathbf{R}}$ from an SRTST is used to show the decidability of the equivalence of SRTST. The both constructions are basically *component-wise*: the regular look-ahead automaton of a $\mathbf{yDT}^{\mathbf{R}}$ M corresponds to the state-transition functions δ_c, δ_r of an SRTST T (also see Remark 20); rules of M correspond to the variable-update functions ρ_c, ρ_r of T ; and *Init* of M corresponds to F of T .

4.1 The construction of SRTST from $\mathbf{yDT}^{\mathbf{R}}$

We construct a *bottom-up* SRTST T from a $\mathbf{yDT}^{\mathbf{R}}$ M ; an SRTST T is *bottom-up* [1] if $\delta_c(s, \sigma) = (s_0, p)$ for some p and $\rho_c(s, p, \sigma) = [\gamma := \gamma]_{\gamma \in \Gamma}$ for every s, p and σ , (i.e., if in any call transition T always resets the state s to the initial state and never change the evaluation function α being pushed on the stack). The construction in the next lemma is inspired by the proof of the decidability of the equivalence of $\mathbf{yDT}^{\mathbf{R}}$ s given in [12, Sections 3 and 4].

Lemma 6. *For any $\mathbf{yDT}^{\mathbf{R}}$ M , there exists a bottom-up SRTST T such that $\text{Dom}(T) = \lfloor \text{Dom}(M) \rfloor$ and $\llbracket T \rrbracket(\lfloor t \rfloor) = \llbracket M \rrbracket(t)$ for all $t \in \text{Dom}(M)$.*

Proof. Let $M = (Q, \Sigma, \Delta, \text{Init}, R)$ be a $\mathbf{yDT}^{\mathbf{R}}$ and we assume that its regular look-ahead is given by DBTA $A = (\Sigma, \Pi, \theta)$. Further, w.l.o.g. (see Lemma 12), we can assume that M satisfies the following conditions: (i) for any tree $\sigma(t_1, \dots, t_n)$ and $q \in Q$, $\sigma(t_1, \dots, t_n) \in \text{Dom}(\llbracket q \rrbracket_M)$ iff there exists a $(q, \sigma, (L_1, \dots, L_n))$ -rule in R such that $t_i \in L_i$ for every $i \in [n]$; and (ii) $\text{Dom}(M) = \bigcup_{(\tau, \pi) \in \text{Init}} \mathcal{L}(\pi)$.

We define an equivalent SRTST $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ as follows. (For its behavior, see also the explanation after the lemma.)

Let $m = \max(\{1\} \cup \{\text{rank}_\Sigma(\sigma) \mid \sigma \in \Sigma\})$, $S = P = \Pi^{(\leq m)}$, and $s_0 = ()$. We define $\Gamma = Q(X_m)$, so that $E(\Gamma, \Delta) = \text{Rhs}_{Q, \Delta}(X_m)$. We define the output (partial) function $F : S \rightarrow E(\Gamma, \Delta)$ as $F((\pi)) = \text{Init}(\mathcal{L}(\pi)) \in \text{Rhs}_{Q, \Delta}(X_1)$.

The call state-transition function $\delta_c : S \times \Sigma \rightarrow S \times P$ is defined by $\delta_c(\boldsymbol{\pi}, \sigma) = (s_0, \boldsymbol{\pi})$. The return state-transition function $\delta_r : S \times P \times \Sigma \rightarrow S$ is defined by $\delta_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma) = \boldsymbol{\pi}' \parallel \theta(\sigma, \boldsymbol{\pi})$ for $\boldsymbol{\pi}, \boldsymbol{\pi}' \in \Pi^{(\leq m)}$ and $\sigma \in \Sigma$ such that $|\boldsymbol{\pi}| = \text{rank}_\Sigma(\sigma)$ and $|\boldsymbol{\pi}'| \neq m$, and by $\delta_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma) = s_0$ for the other case of arguments $\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma$.

The call variable-update function $\rho_c : S \times \Sigma \rightarrow \mathcal{A}(\Gamma, \Gamma, \Delta)$ is defined by $\rho_c(\boldsymbol{\pi}, \sigma) = [\gamma := \gamma]_{\gamma \in \Gamma}$. The return variable-update function $\rho_r : S \times P \times \Sigma \rightarrow \mathcal{A}(\Gamma, \Gamma \uplus \bar{\Gamma}, \Delta)$ is defined by

$$\begin{aligned} \rho_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma) = & \left[q(x_k) := \overline{q(x_k)} \right]_{q \in Q, k \leq |\boldsymbol{\pi}'|} \\ & \uplus \left[q(x_{|\boldsymbol{\pi}'|+1}) := \underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi}) \right]_{q \in Q} \\ & \uplus \left[q(x_k) := \varepsilon \right]_{q \in Q, |\boldsymbol{\pi}'|+1 < k \leq m} \end{aligned}$$

for $\boldsymbol{\pi}, \boldsymbol{\pi}' \in \Pi^{(\leq m)}$ and $\sigma \in \Sigma$ such that $|\boldsymbol{\pi}| = \text{rank}_\Sigma(\sigma)$ and $|\boldsymbol{\pi}'| \neq m$, and by $\rho_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma) = \alpha_\varepsilon$ for the other case of arguments $\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma$. Above, the function $\underline{\text{rhs}} : \bigcup_{n \in \mathbb{N}} (Q \times \Sigma^{(n)} \times \Pi^n) \rightarrow E(\Gamma, \Delta)$ is defined by

$$\underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi}) = \begin{cases} \text{rhs}(q, \sigma, \boldsymbol{\pi}) & ((q, \sigma, \boldsymbol{\pi})\text{-rule is defined}) \\ \varepsilon & (\text{otherwise}) \end{cases}$$

where $\text{rhs}(q, \sigma, \boldsymbol{\pi}) \in \text{Rhs}_{Q, \Delta}(X_n) \subseteq E(\Gamma, \Delta)$. Above, ε in the definitions of ρ_r and $\underline{\text{rhs}}$ are not used in the actual computation. We control “definedness” by the determinism of the DBTA A and the above assumptions (i) and (ii) for M .

The equivalence of M and T follows from Lemmas 15 and 16. \square

The construction of T is designed to behave for each input symbol as follows. Let $\sigma'(t'_1, \dots, t'_n)$ be a subtree of an input tree, and $t'_i = \sigma(t_1, \dots, t_n)$.

Call symbol $\langle \sigma \rangle$: By the definitions of δ_c and ρ_c above, in general a call transition is $(\boldsymbol{\pi}', A, \beta) \xrightarrow{\langle \sigma \rangle} ((\boldsymbol{\pi}', \beta)A, \alpha_\varepsilon)$. Suppose that T starts the computation of $t'_i = \sigma(t_1, \dots, t_n)$. The computation so far for t'_1, \dots, t'_{i-1} is recorded in $\boldsymbol{\pi}'$ and β and the further earlier computation is recorded in A . Then the call transition by $\langle \sigma \rangle$ saves the record $(\boldsymbol{\pi}', \beta)$ to the stack.

Return symbol $\sigma \rangle$: A return transition is basically of the following form:

$(\boldsymbol{\pi}, (\boldsymbol{\pi}', \beta)A, \alpha) \xrightarrow{\sigma \rangle} (\boldsymbol{\pi}' \parallel \theta(\sigma, \boldsymbol{\pi}), A, \alpha')$. Suppose that T is finishing the computation of some child tree $t'_i = \sigma(t_1, \dots, t_n)$.

The state-transition function δ_r simulates the DBTA A as follows. In the transition $\delta_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma) = \boldsymbol{\pi}' \parallel \theta(\sigma, \boldsymbol{\pi})$, $\boldsymbol{\pi} = (\pi_1, \dots, \pi_n)$ is a tuple of A -states and π_1, \dots, π_n accept t_1, \dots, t_n , respectively. Hence $\theta(\sigma, \boldsymbol{\pi})$ is an A -state which accepts $t'_i = \sigma(t_1, \dots, t_n)$. Likewise, $\boldsymbol{\pi}'$ is a tuple of A -states which accept t'_1, \dots, t'_{i-1} , respectively. In this way, δ_r plays the role of regular look-ahead, and each component of a state $\boldsymbol{\pi}$ of T (and of a stack symbol $\boldsymbol{\pi}'$ on a stack) represents a regular language of the look-ahead.

According to the definitions of the semantics of an SRTST and of ρ_r ,

$$\begin{aligned} \alpha' = \rho_r(\boldsymbol{\pi}, \boldsymbol{\pi}', \sigma)(\alpha \uplus \bar{\beta}) = & \left[q(x_k) := \beta(q(x_k)) \right]_{q \in Q, k \leq |\boldsymbol{\pi}'|} \\ & \uplus \left[q(x_{|\boldsymbol{\pi}'|+1}) := \underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi})\alpha \right]_{q \in Q} \\ & \uplus \left[q(x_k) := \varepsilon \right]_{q \in Q, |\boldsymbol{\pi}'|+1 < k \leq m} . \end{aligned}$$

Here, variable values of α are the result of computation of t_1, \dots, t_n by M (i.e., by every $q \in Q$), and hence $\underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi})\alpha$ is the result of computation of $t'_i = \sigma(t_1, \dots, t_n)$ by q ; note that $q(x_{|\boldsymbol{\pi}'|+1}) = q(x_i)$. Likewise, β is the result of computation of t'_1, \dots, t'_{i-1} by M . In this way, T computes as M does, and the result is recorded in the current evaluation function α of a configuration (and evaluation function β on a stack).

Note that in our construction the finiteness of the width of trees is used for the finiteness of sets S , P , and Γ , in both δ_r and ρ_r .

See Appendix D for an example of the above construction (Example 29).

4.2 The construction of yDT^{R} from SRTST

For an SRTST T , $s_0, \dots, s_n \in S$, and nested words $w_1 \dots, w_n$, we write $s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \dots \xrightarrow{w_n} s_n$ if $(s_0, \Lambda_0, \alpha_0) \xrightarrow{w_1} (s_1, \Lambda_1, \alpha_1) \dots \xrightarrow{w_n} (s_n, \Lambda_n, \alpha_n)$ for some Λ_i and α_i ($i = 0, \dots, n$). We write $s \xrightarrow{\langle \sigma \rangle_p} s'$ if $\delta_c(s, \sigma) = (s', p)$, and $s \xrightarrow{\langle \sigma \rangle_p} s'$ if $\delta_r(s, p, \sigma) = s'$.

Lemma 7. *For any SRTST T , there exists a yDT^{R} M such that $\text{Dom}(M) = \llbracket \text{Dom}(T) \rrbracket$ and $\llbracket M \rrbracket(\llbracket w \rrbracket) = \llbracket T \rrbracket(w)$ for all $w \in \text{Dom}(T)$.*

Proof. Let $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ be an SRTST. We define a yDT^{R} $M = (Q, \Sigma, \Delta, \text{Init}, R)$ with a regular look-ahead NBTA $A = (\Sigma, \Pi, \theta)$.

First we define a predicate vst (stands for *valid state transition*): for given $((s_{n+1}^c, \sigma, s_{n+1}), (s_1, \sigma_1, s_1^r), \dots, (s_n, \sigma_n, s_n^r)) \in \bigcup_{n \in \mathbb{N}} (S \times \Sigma^{(n)} \times S) \times (S \times \Sigma \times S)^n$,

$$\begin{aligned} & \text{vst}((s_{n+1}^c, \sigma^{(n)}, s_{n+1}), (s_1, \sigma_1, s_1^r), \dots, (s_n, \sigma_n, s_n^r)) \text{ if} \\ & s_{n+1}^c \xrightarrow{\langle \sigma \rangle_p} s_1 \xrightarrow{\langle \sigma_1 \rangle_{p_1}} s_1', \quad s_1^r \xrightarrow{\langle \sigma_1 \rangle_{p_1}} s_2 \xrightarrow{\langle \sigma_2 \rangle_{p_2}} s_2', \quad s_2^r \xrightarrow{\langle \sigma_2 \rangle_{p_2}} s_3 \dots \\ & \dots s_n \xrightarrow{\langle \sigma_n \rangle_{p_n}} s_n', \quad s_n^r \xrightarrow{\langle \sigma_n \rangle_{p_n}} s_{n+1} \end{aligned} \quad (1)$$

where $s'_i \in S$ and $p, p_i \in P$ are given by the call-transitions in (1). Note that $\text{vst}((s_1^c, \sigma^{(0)}, s_1))$ iff $s_1^c \xrightarrow{\langle \sigma \rangle_p} s_1$, when $n = 0$. Eq. (1) holds if we have

$$\begin{aligned} & s_{n+1}^c \xrightarrow{\langle \sigma \rangle} s_1 \xrightarrow{\langle \sigma_1 \rangle} s_1' \xrightarrow{w_1} s_1^r \xrightarrow{\langle \sigma_1 \rangle} s_2 \xrightarrow{\langle \sigma_2 \rangle} s_2' \xrightarrow{w_2} s_2^r \xrightarrow{\langle \sigma_2 \rangle} s_3 \dots \\ & \dots s_n \xrightarrow{\langle \sigma_n \rangle} s_n' \xrightarrow{w_n} s_n^r \xrightarrow{\langle \sigma_n \rangle} s_{n+1} \end{aligned} \quad (2)$$

for some well-matched w_i . Conversely, to obtain (2) we need the condition vst recursively for the parts $s_i \xrightarrow{\langle \sigma_i \rangle} s'_i \xrightarrow{w_i} s_i^r$, which leads to the next definition. Note that (1) and (2) extend with $\xrightarrow{\langle \sigma \rangle_p} s'$ and $\xrightarrow{\langle \sigma \rangle} s'$ for some unique s' , respectively.

States of NBTA Let $\Pi_0 \triangleq \emptyset$, and for $i > 0$,

$$\begin{aligned} \Pi_i & \triangleq \Pi_{i-1} \cup \{(s^c, \sigma^{(n)}, s^r) \in S \times \Sigma \times S \mid n \in \mathbb{N} \wedge \\ & \exists (\pi_1, \dots, \pi_n) \in (\Pi_{i-1})^n. \text{vst}((s^c, \sigma, s^r), \pi_1, \dots, \pi_n)\}. \end{aligned}$$

Thus we have defined a chain: $\Pi_0 \subseteq \Pi_1 \subseteq \Pi_2 \subseteq \dots \subseteq S \times \Sigma \times S$, and we define the set of states as $\Pi \triangleq \bigcup_i \Pi_i \subseteq S \times \Sigma \times S$, which is finite. Then, $(s_{n+1}^c, \sigma^{(n)}, s_{n+1}) \in \Pi$ iff the T -transition (2) exists.

Transition function of NBTA The transition function $\theta : \bigcup_{n \in \mathbb{N}} (\Sigma^{(n)} \times \Pi^n) \rightarrow 2^\Pi$ is defined by

$$\theta(\sigma^{(n)}, (\pi_1, \dots, \pi_n)) \triangleq \{(s^c, \sigma, s^r) \in S \times \Sigma \times S \mid \text{vst}((s^c, \sigma, s^r), \pi_1, \dots, \pi_n)\}.$$

This ensures that a tree $\sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$ is accepted by an A -state (s^c, σ, s^r) iff a transition $s^c \xrightarrow{\langle \sigma \mid t_1 \dots t_n \rangle} s^r \xrightarrow{\sigma} s'$ exists; any $t \in \mathcal{T}_\Sigma$ is accepted by at least one state of A (though $F(s')$ is not necessarily defined).

Rules We define $Q = S \times S \times \Gamma$. For every $(s^c, \sigma, s^r) \in \Pi$, $\gamma \in \Gamma$, and $\pi_1, \dots, \pi_n \in \Pi$ such that $(s^c, \sigma, s^r) \in \theta(\sigma, (\pi_1, \dots, \pi_n))$, the following rule is added in R :

$$(s^c, s^r, \gamma)(\sigma(x_1, \dots, x_n)) \rightarrow \mathcal{W}(\pi_1, \dots, \pi_n)(\gamma) \quad \langle \pi_1, \dots, \pi_n \rangle$$

where $\mathcal{W} : \Pi^n \rightarrow \mathcal{A}(\Gamma, Q(X_n), \Delta)$ is defined from ρ_c and ρ_r as follows, and note that $\mathcal{W}(\pi_1, \dots, \pi_n)(\gamma) \in E(Q(X_n), \Delta) = \text{Rhs}_{Q, \Delta}(X_n)$.

W.l.o.g., we assume that $Q(X_n) \cap (\Gamma \uplus \bar{\Gamma}) = \emptyset$. For $\pi_i = (s_i^c, \sigma_i, s_i^r)$ ($i \in [n]$), let $\delta_c(s_i^c, \sigma_i) = (s_i, p_i)$. Then

$$\mathcal{W}(\pi_1, \dots, \pi_n) \triangleq \beta_n^r(\eta_n \uplus (\beta_n^c(\dots(\beta_1^r(\eta_1 \uplus (\beta_1^c \alpha_\varepsilon^\Gamma))) \dots))) \quad (3)$$

$$\begin{aligned} \text{where: } \alpha_\varepsilon^\Gamma &= [\gamma := \varepsilon]_{\gamma \in \Gamma} && \in \mathcal{A}(\Gamma, Q(X_n), \Delta) \\ \beta_i^c &\triangleq \overline{\rho_c(s_i^c, \sigma_i)} && \in \mathcal{A}(\bar{\Gamma}, \Gamma, \Delta) \\ \eta_i &\triangleq [\gamma := (s_i^c, s_i^r, \gamma)(x_i)]_{\gamma \in \Gamma} && \in \mathcal{A}(\Gamma, Q(X_n), \Delta) \\ \beta_i^r &\triangleq \overline{\rho_r(s_i^r, p_i, \sigma_i)} && \in \mathcal{A}(\Gamma, \Gamma \uplus \bar{\Gamma}, \Delta). \end{aligned}$$

The intuition for the above rule is as follows. Recall that the computation of T is top-down and bottom up, by call and return transitions, respectively. Also recall that state-transition functions δ_c and δ_r are already simulated by regular look-ahead, resulting $\pi_i = (s_i^c, \sigma_i, s_i^r)$ ($i \in [n]$). In (3), β_1^c (with $\alpha_\varepsilon^\Gamma$) corresponds to the call transition by the root σ_1 of the leftmost subtree x_1 :

$$(s_1^c, A, \alpha_\varepsilon^\Gamma) \xrightarrow{\langle \sigma_1 \rangle} (s'_1, (p_1, \rho_c(s_1^c, \sigma_1) \alpha_\varepsilon^\Gamma) A, \alpha_\varepsilon^\Gamma)$$

where s'_1 and A are some state and stack, and the current evaluation function before this transition is $\alpha_\varepsilon^\Gamma$ because the configuration is just after the call transition for the parent σ . Then, η_1 is the recursive computation by T of the subtree x_1 . And then $\beta_1^r(\eta_1 \uplus (\beta_1^c \alpha_\varepsilon^\Gamma))$ corresponds to the return transition

$$(s_1^r, (p_1, \rho_c(s_1^c, \sigma_1) \alpha_\varepsilon^\Gamma) A, \eta_1) \xrightarrow{\langle \sigma_1 \rangle} (s_2^c, A, \beta_1^r(\eta_1 \uplus (\beta_1^c \alpha_\varepsilon^\Gamma)))$$

where note that $\overline{\rho_c(s_1^c, \sigma_1) \alpha_\varepsilon^\Gamma} = \overline{\rho_c(s_1^c, \sigma_1)} \alpha_\varepsilon^\Gamma = \beta_1^c \alpha_\varepsilon^\Gamma$. Repeating this also for the remaining sibling subtrees x_2, \dots, x_n , we obtain (3).

Initial sequences Finally, we define *Init* in a similar way to *R*:

$$\text{Init} = \bigcup_{\sigma \in \Sigma} \left\{ (F(s')\beta_{s^r, p, \sigma}^r(\eta_{s^r} \uplus (\beta_\sigma^c \alpha_\varepsilon^\Gamma)), (s_0, \sigma, s^r)) \mid \right. \\ \left. (s_0, \sigma, s^r) \in \Pi, \quad s_0 \xrightarrow{\langle \sigma \rangle_p} s_1, \quad s^r \xrightarrow{\langle \sigma \rangle_p} s' \in \text{Dom}(F) \right\}$$

where: (i) s_0 is the initial state of T , and s_1 , s' , and p are given by the transitions, (ii) $\beta_\sigma^c \triangleq \overline{\rho_c(s_0, \sigma)}$, (iii) $\eta_{s^r} \triangleq [\gamma := (s_0, s^r, \gamma)(x_1)]_{\gamma \in \Gamma}$, and (iv) $\beta_{s^r, p, \sigma}^r \triangleq \rho_r(s^r, p, \sigma)$.

The intuition is as follows. Let $t = \sigma(t_1, \dots, t_n)$ be an input tree, and

$$(s_0, \varepsilon, \alpha_\varepsilon^\Gamma) \xrightarrow{\langle \sigma \rangle} (s_1, (p, \rho_c(s_0, \sigma)\alpha_\varepsilon^\Gamma), \alpha_\varepsilon^\Gamma) \xrightarrow{\lfloor t_1 \rfloor} \dots \\ \dots \xrightarrow{\lfloor t_n \rfloor} (\tilde{s}^r, (p, \rho_c(s_0, \sigma)\alpha_\varepsilon^\Gamma), \tilde{\eta}) \xrightarrow{\langle \sigma \rangle} (\tilde{s}', \varepsilon, \rho_r(\tilde{s}^r, p, \sigma)(\tilde{\eta} \uplus (\beta_\sigma^c \alpha_\varepsilon^\Gamma)))$$

be the transition for $\lfloor t \rfloor$. Now t , \tilde{s}^r , $\tilde{\eta}$, \tilde{s}' , and $\rho_r(\tilde{s}^r, p, \sigma)$ respectively correspond to x_1 , s^r , η_{s^r} , s' , and $\beta_{s^r, p, \sigma}^r = \rho_r(s^r, p, \sigma)$ in the above definition. Here η_{s^r} involves $\llbracket (s_0, s^r, \gamma) \rrbracket_M(t)$, which is computed as in **Rules** above.

The equivalence of M and T follows from Lemmas 23 and 27. \square

See Appendix D for an example of the above construction (Example 30).

4.3 Expressiveness and Decidability of Equivalence

Combining Lemmas 6 and 7, we can conclude:

Theorem 8. *SRTSTs and yDT^Rs are equi-expressive.*

Theorem 9. *For all SRTST T , there exists a bottom-up SRTST T' such that $\llbracket T \rrbracket = \llbracket T' \rrbracket$. Thus, SRTSTs and bottom-up SRTSTs are equi-expressive.*

The STT_{sur}-version of Theorem 9 is given in [1, Theorem 3.7], where, though, it was shown directly. As an immediate consequence of Lemma 7 and Theorem 3, we have:

Theorem 10. *Given SRTSTs T_1 and T_2 , it is decidable whether $\llbracket T_1 \rrbracket = \llbracket T_2 \rrbracket$.*

Concluding remark By dropping the condition of sur from STT_{sur}, we obtain the notion of an STT. We hope that our method can be applied to a similar result to Theorem 8, modified from SRTST to a similar model to STT whose input and output are ranked trees. If we further consider STT, whose input and output are *unranked* trees, it is not clear what model we should compare STT with, to solve the open problem of the decidability of the equivalence for STTs.

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A SRTST_{sur}, STST_{sur}, and MSO-definability

Here, as an immediate corollary of results in [1], we explain that MSO-definable ranked-tree-to-string transducers and SRTST_{sur}s are equi-expressive.

For the notions in this section, see [1], but note that, in [1]:

- (i) the word “tree” means a well-matched nested word, rather than well-labeled nested word,
- (ii) ranked trees are considered just as binary trees, just for presentation,
- (iii) the notion of a nested word (in [1]) consists also of *internal symbols*, and ranked trees are embedded in nested words that contain no internal symbol (this is the reason why we omit the notion of an internal symbol from our notion of a nested word),

(iv) strings are embedded in nested words as strings of internal symbols.

Here we denote by $\langle \Sigma \rangle^i$ the set of well-nested words (with internal symbols) in [1] and denote by $\langle \Sigma \rangle$ the set of well-nested words defined in the current paper. There is an obvious embedding $e^i : \langle \Sigma \rangle \rightarrow \langle \Sigma \rangle^i$. Also we write $e^{\text{str}} : \Delta^* \rightarrow \langle \Delta \rangle^i$ for the embedding of (iv) above. Given $f : \langle \Sigma \rangle^i \rightarrow \Delta^*$, for $X = \text{STT}_{\text{sur}} / \text{MSO}$, we say f is *X-definable* if $e^{\text{str}} \circ f : \langle \Sigma \rangle^i \rightarrow \Delta^* \hookrightarrow \langle \Delta \rangle^i$ is X-definable. Also, given $f : [\mathcal{T}_\Sigma] \rightarrow \Delta^*$, f is called *MSO-definable* if there exists MSO-definable $g : \langle \Sigma \rangle^i \rightarrow \langle \Delta \rangle^i$ such that $e^{\text{str}} \circ f = g|_{[\mathcal{T}_\Sigma]}$.

In [1], the authors considered a variation of the notion of an STT_{sur} , i.e., that of an STST_{sur} , whose input and output are well-matched nested words and strings, respectively. (Recall that both the input and output of an STT_{sur} are well-matched nested words.) We can restrict the notion of an STST_{sur} with single-use restriction, which we call an $\text{SRTST}_{\text{sur}}$. The syntax for $\text{SRTST}_{\text{sur}}$ s is the same as that for STST_{sur} s except that: (i) the input in the semantics is restricted to ranked nested words, and (ii) since the input does not involve internal symbols, we eliminate redundant notions (an internal state-transition function and an internal variable-update function) from the definition.

Corollary 11 ([1]). *Given $g : \langle \Sigma \rangle^i \rightarrow \Delta^*$, g is MSO-definable iff g is STST_{sur} -definable. Therefore, given $f : [\mathcal{T}_\Sigma] \rightarrow \Delta^*$, f is MSO-definable iff f is $\text{SRTST}_{\text{sur}}$ -definable.*

Proof. The latter part trivially follows from the former part. The former part is nothing but a combination of the following two results: Given $g : \langle \Sigma \rangle^i \rightarrow \Delta^*$, g is STT_{sur} -definable iff g is STST_{sur} -definable [1, Theorem 3.18]. Given $g : \langle \Sigma \rangle^i \rightarrow \langle \Delta \rangle^i$, g is MSO-definable iff g is STT_{sur} -definable [1, Theorem 4.6]. \square

B Lemmas for Section 4.1

Lemma 12. *Given a yDT^{R} $M = (Q, \Sigma, \Delta, \text{Init}, R)$, there exists a yDT^{R} $M' = (Q, \Sigma, \Delta, \text{Init}', R')$ such that $\llbracket M \rrbracket = \llbracket M' \rrbracket$ and M' satisfies the following conditions:*

(i) For any tree $\sigma(t_1, \dots, t_n)$ and $q \in Q$,

$$\begin{aligned} \sigma(t_1, \dots, t_n) \in \text{Dom}(\llbracket q \rrbracket_{M'}) &\iff \\ \text{there exists a } (q, \sigma, (L_1, \dots, L_n))\text{-rule in } R' &\text{ such that } t_i \in L_i \text{ for every } i \in [n]. \end{aligned}$$

(ii) $\text{Dom}(M') = \bigsqcup_{(\tau, L) \in \text{Init}'} L$.

Proof. Let $M = (Q, \Sigma, \Delta, \text{Init}, R)$. We define $M' = (Q, \Sigma, \Delta, \text{Init}', R')$ as follows.

$$\begin{aligned} \text{Init}' &\triangleq \left\{ (\tau, L') \mid (\tau, L) \in \text{Init}, \right. \\ &\quad \left. L' = L \cap \bigcap_{q' \in Q, q'(x_1) \text{ occurs in } \tau} \text{Dom}(\llbracket q' \rrbracket_M) \neq \emptyset \right\} \end{aligned}$$

$$R' \triangleq \left\{ \begin{array}{l} q(\sigma(x_1, \dots, x_n)) \rightarrow \tau \quad \langle L'_1, \dots, L'_n \rangle \quad \Big| \\ (q(\sigma(x_1, \dots, x_n)) \rightarrow \tau \quad \langle L_1, \dots, L_n \rangle) \in R, \\ L'_i = L_i \cap \bigcap_{q' \in Q, q'(x_i) \text{ occurs in } \tau} \text{Dom}(\llbracket q' \rrbracket_M) \neq \emptyset \end{array} \right\}$$

Above, $\text{Dom}(\llbracket q' \rrbracket_M)$ is (effectively) a regular tree language (Corollary 2.7 in [5]) and hence so are L' and L'_i .

First let us check that: (i) for $(\tau_1, L'_1) \neq (\tau_2, L'_2)$ in Init' , we have $L'_1 \cap L'_2 = \emptyset$, and (ii) for $(q, \sigma, \tau_1, (L'_{1,1}, \dots, L'_{1,n})) \neq (q, \sigma, \tau_2, (L'_{2,1}, \dots, L'_{2,n}))$ in R' , we have $L'_{1,i} \cap L'_{2,i} = \emptyset$ for some i . For (i), suppose $(\tau_1, L'_1) \neq (\tau_2, L'_2)$, and for each i let L_i be a witness for $L'_i \in \text{Init}'$. In the case where $\tau_1 = \tau_2$, we must have $L'_1 \neq L'_2$, which implies $L_1 \neq L_2$ (by contraposition) and hence $(\tau_1, L_1) \neq (\tau_2, L_2)$. In the case where $\tau_1 \neq \tau_2$, trivially $(\tau_1, L_1) \neq (\tau_2, L_2)$. Thus in any case we have $(\tau_1, L_1) \neq (\tau_2, L_2)$, and hence $L'_1 \cap L'_2 \subseteq L_1 \cap L_2 = \emptyset$. We can check (ii) in the same way.

Now, for any tree $\sigma(t_1, \dots, t_n)$ and $q \in Q$,

$$\sigma(t_1, \dots, t_n) \in \text{Dom}(\llbracket q \rrbracket_M) \iff$$

there exists a $(q, \sigma, (L'_1, \dots, L'_n))$ -rule in R' such that $t_i \in L'_i$ for every $i \in [n]$.

Thus the item (i) is equivalent to the following:

$$\sigma(t_1, \dots, t_n) \in \text{Dom}(\llbracket q \rrbracket_{M'}) \iff \sigma(t_1, \dots, t_n) \in \text{Dom}(\llbracket q \rrbracket_M) \quad \text{for all } q \in Q.$$

This and the following

$$\llbracket q \rrbracket_{M'}(\sigma(t_1, \dots, t_n)) = \llbracket q \rrbracket_M(\sigma(t_1, \dots, t_n)) \quad \text{for all } q \in Q$$

can be shown easily by induction on $\sigma(t_1, \dots, t_n)$. From these, the item (ii) (which is equivalent to $\text{Dom}(M') = \text{Dom}(M)$) and $\llbracket M' \rrbracket = \llbracket M \rrbracket$ immediately follow. \square

Lemma 13. *Let $M = (Q, \Sigma, \Delta, \text{Init}, R)$ be a yDT^R , $n \in \mathbb{N}$, $t_1, \dots, t_n \in \mathcal{T}_\Sigma$, $\Gamma' \subseteq Q(X_n)$, and $\tau \in E(\Gamma', \Delta) \subseteq \text{Rhs}_{Q, \Delta}(X_n)$. Then if $t_i \in \text{Dom}(\llbracket q \rrbracket_M)$ for every $q(x_i) \in \Gamma'$, we have*

$$\llbracket \tau \rrbracket_M(t_1, \dots, t_n) = \tau[q(x_i) := \llbracket q \rrbracket_M(t_i)]_{q(x_i) \in \Gamma'}.$$

Proof. Trivial (induction on the length of τ). \square

Let $M = (Q, \Sigma, \Delta, \text{Init}, R)$ be a yDT^R that satisfies the two properties of M' in Lemma 12, and $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ be the SRTST constructed by the proof of Lemma 6 from M .

The next lemma describes how the semantics of M and that of T are related. We define

$$\llbracket q \rrbracket_M^\varepsilon(t) \triangleq \begin{cases} \llbracket q \rrbracket_M(t) & (t \in \text{Dom}(\llbracket q \rrbracket_M)) \\ \varepsilon & (\text{otherwise}). \end{cases}$$

Lemma 14. For any $t \in \mathcal{T}_\Sigma$ and configuration $(\boldsymbol{\pi}, \Lambda, \alpha)$ where $|\boldsymbol{\pi}| \neq m$, we have $(\boldsymbol{\pi}, \Lambda, \alpha) \xrightarrow{[t]} (\boldsymbol{\pi} \parallel \hat{\theta}(t), \Lambda, \alpha')$ with

$$\begin{aligned} \alpha' = & [q(x_k) := \alpha(q(x_k))]_{q \in Q, 1 \leq k \leq |\boldsymbol{\pi}|} \uplus [q(x_{|\boldsymbol{\pi}+1}) := \llbracket q \rrbracket_M^\varepsilon(t)]_{q \in Q} \\ & \uplus [q(x_k) := \varepsilon]_{q \in Q, |\boldsymbol{\pi}+1| < k \leq m} . \end{aligned}$$

Proof. The proof proceeds by induction on t . Let $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$. The transition from $(\boldsymbol{\pi}, \Lambda, \alpha)$ by $[t]$ is as follows, where we use induction hypothesis:

$$\begin{aligned} & (\boldsymbol{\pi}, \Lambda, \alpha) \\ \xrightarrow{\langle \sigma \rangle} & ((\boldsymbol{\pi}, \alpha) \Lambda, \alpha_\varepsilon) \\ \xrightarrow{[t_1]} & \left((\hat{\theta}(t_1)), (\boldsymbol{\pi}, \alpha) \Lambda, [q(x_1) := \llbracket q \rrbracket_M^\varepsilon(t_1)]_{q \in Q} \uplus [q(x_k) := \varepsilon]_{q \in Q, 1 < k \leq m} \right) \\ & \dots \\ \xrightarrow{[t_n]} & \left((\hat{\theta}(t_1), \dots, \hat{\theta}(t_n)), (\boldsymbol{\pi}, \alpha) \Lambda, \right. \\ & \left. [q(x_k) := \llbracket q \rrbracket_M^\varepsilon(t_k)]_{q \in Q, 1 \leq k \leq n} \uplus [q(x_k) := \varepsilon]_{q \in Q, n < k \leq m} \right) \\ \xrightarrow{\langle \sigma \rangle} & (\boldsymbol{\pi} \parallel \theta(\sigma, \boldsymbol{\pi}''), \Lambda, \rho_r(\boldsymbol{\pi}'', \boldsymbol{\pi}, \sigma) \alpha'') \end{aligned}$$

where

$$\begin{aligned} \boldsymbol{\pi}'' & \triangleq (\hat{\theta}(t_1), \dots, \hat{\theta}(t_n)) \\ \alpha'' & \triangleq [q(x_k) := \llbracket q \rrbracket_M^\varepsilon(t_k)]_{q \in Q, 1 \leq k \leq n} \uplus [q(x_k) := \varepsilon]_{q \in Q, n < k \leq m} \uplus \bar{\alpha} \\ \bar{\alpha} & = [\overline{q(x_k)} := \alpha(q(x_k))]_{q \in Q, 1 \leq k \leq m} . \end{aligned}$$

Here, as required, we have $\theta(\sigma, \boldsymbol{\pi}'') = \hat{\theta}(t)$ by the definition of $\hat{\theta}$ (for DBTA).

By the definition of ρ_r given in Section 4.1, we have

$$\begin{aligned} & \rho_r(\boldsymbol{\pi}'', \boldsymbol{\pi}, \sigma) \alpha'' \\ = & \left(\begin{array}{l} [q(x_k) := \overline{q(x_k)}]_{q \in Q, 1 \leq k \leq |\boldsymbol{\pi}|} \\ \uplus [q(x_{|\boldsymbol{\pi}+1}) := \underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi}'')]_{q \in Q} \\ \uplus [q(x_k) := \varepsilon]_{q \in Q, |\boldsymbol{\pi}+1| < k \leq m} \end{array} \right) \alpha'' \\ = & [q(x_k) := \overline{q(x_k)} \alpha'']_{q \in Q, 1 \leq k \leq |\boldsymbol{\pi}|} \\ & \uplus [q(x_{|\boldsymbol{\pi}+1}) := \underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi}'') \alpha'']_{q \in Q} \\ & \uplus [q(x_k) := \varepsilon \alpha'']_{q \in Q, |\boldsymbol{\pi}+1| < k \leq m} \\ = & [q(x_k) := \alpha(q(x_k))]_{q \in Q, 1 \leq k \leq |\boldsymbol{\pi}|} \\ & \uplus [q(x_{|\boldsymbol{\pi}+1}) := \underline{\text{rhs}}(q, \sigma, \boldsymbol{\pi}'') \alpha'']_{q \in Q} \\ & \uplus [q(x_k) := \varepsilon]_{q \in Q, |\boldsymbol{\pi}+1| < k \leq m} . \end{aligned}$$

Then the remaining to show is that, for any $q \in Q$, $\underline{\text{rhs}}(q, \sigma, \pi'')\alpha'' = \llbracket q \rrbracket_M(t)$ if $t \in \text{Dom}(\llbracket q \rrbracket_M)$; and $\underline{\text{rhs}}(q, \sigma, \pi'')\alpha'' = \varepsilon$ if $t \notin \text{Dom}(\llbracket q \rrbracket_M)$.

Since M satisfies the property (i) in Lemma 12 and since A is a DBTA, $t \in \text{Dom}(\llbracket q \rrbracket_M)$ iff (q, σ, π'') -rule is defined, and furthermore if this is the case, then, for any $q'(x_k)$ in

$$\Gamma' \triangleq \{q'(x_k) \in Q(X_n) \mid q'(x_k) \text{ occurs in } \text{rhs}(q, \sigma, \pi'')\},$$

$\llbracket q' \rrbracket_M(t_k)$ is defined and hence $\llbracket q' \rrbracket_M^\varepsilon(t_k) = \llbracket q' \rrbracket_M(t_k)$. Now, recall the definition of $\underline{\text{rhs}}$:

$$\underline{\text{rhs}}(q, \sigma, \pi'') \triangleq \begin{cases} \text{rhs}(q, \sigma, \pi'') & ((q, \sigma, \pi'')\text{-rule is defined}) \\ \varepsilon & (\text{otherwise}). \end{cases}$$

Then, if $t \in \text{Dom}(\llbracket q \rrbracket_M)$,

$$\begin{aligned} \underline{\text{rhs}}(q, \sigma, \pi'')\alpha'' &= \text{rhs}(q, \sigma, \pi'')\alpha'' \\ &= \text{rhs}(q, \sigma, \pi'') [q'(x_k) := \llbracket q' \rrbracket_M^\varepsilon(t_k)]_{q'(x_k) \in \Gamma'} \\ &= \text{rhs}(q, \sigma, \pi'') [q'(x_k) := \llbracket q' \rrbracket_M(t_k)]_{q'(x_k) \in \Gamma'} \\ &= \llbracket \text{rhs}(q, \sigma, \pi'') \rrbracket_M(t_1, \dots, t_n) && \text{(by Lemma 13)} \\ &= \llbracket q \rrbracket_M(t) \end{aligned}$$

and if $t \notin \text{Dom}(\llbracket q \rrbracket_M)$,

$$\underline{\text{rhs}}(q, \sigma, \pi'')\alpha'' = \varepsilon\alpha'' = \varepsilon. \quad \square$$

Lemma 15. *The domain of $\llbracket T \rrbracket$ is isomorphic to the domain of $\llbracket M \rrbracket$ by $\lfloor - \rfloor$.*

Proof. We have:

$$\begin{aligned} t \in \text{Dom}(M) &\iff t \in \bigcup_{(\tau, \pi) \in \text{Init}} \mathcal{L}(\pi) && \text{(by Lemma 12 - (ii))} \\ &\iff \hat{\theta}(t) \in \text{Dom}(\text{Init}) && (t \in \mathcal{L}(\pi) \iff \hat{\theta}(t) = \pi \text{ by definition}) \\ &\iff (\hat{\theta}(t)) \in \text{Dom}(F) && \text{(by the definition of } F) \\ &\iff \lfloor t \rfloor \in \text{Dom}(T). && \text{(by Lemma 14)} \end{aligned}$$

□

Lemma 16. $\llbracket T \rrbracket(\lfloor t \rfloor) = \llbracket M \rrbracket(t)$ for every $t \in \text{Dom}(M)$.

Proof. By Lemma 14, we have $((), \varepsilon, \alpha_\varepsilon) \xrightarrow{\lfloor t \rfloor} ((\hat{\theta}(t)), \varepsilon, \alpha')$ with

$$\alpha' = [q(x_1) := \llbracket q \rrbracket_M^\varepsilon(t)]_{q \in Q} \uplus [q(x_k) := \varepsilon]_{q \in Q, 1 < k \leq m}.$$

Let $t = \sigma(t_1, \dots, t_n)$. Since $t \in \text{Dom}(M)$ and M satisfies the property (ii) in Lemma 12, $\text{Init}(\hat{\theta}(t))$ is defined, and furthermore for any $q(x_1)$ in

$$\Gamma' \triangleq \{q(x_1) \in Q(X_1) \mid q(x_1) \text{ occurs in } \text{Init}(\hat{\theta}(t))\},$$

$\llbracket q \rrbracket_M(t)$ is defined, so that $\llbracket q \rrbracket_M^\varepsilon(t) = \llbracket q \rrbracket_M(t)$. Then

$$\begin{aligned} \llbracket T \rrbracket(\lfloor t \rfloor) &= F((\hat{\theta}(t)))\alpha' \\ &= \text{Init}(\hat{\theta}(t)) [q(x_1) := \llbracket q \rrbracket_M^\varepsilon(t)]_{q(x_1) \in \Gamma'} \\ (\text{where recall that } F((\hat{\theta}(t))) &= \text{Init}(\hat{\theta}(t)) \in \text{Rhs}_{Q,\Delta}(X_1) (\subseteq \text{Rhs}_{Q,\Delta}(X_m))) \\ &= \text{Init}(\hat{\theta}(t)) [q(x_1) := \llbracket q \rrbracket_M(t)]_{q(x_1) \in \Gamma'} \\ &= \llbracket \text{Init}(\hat{\theta}(t)) \rrbracket_M(t) && \text{(by Lemma 13)} \\ &= \llbracket M \rrbracket(t) && \square \end{aligned}$$

C Lemmas for Section 4.2

Let $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ be an SRTST and $M = (Q, \Sigma, \Delta, \text{Init}, R)$ be the yDT^R constructed in the proof of Lemma 7 from T .

First recall that, for an SRTST T , $s_0, \dots, s_n \in S$, and nested words $w_1 \dots, w_n$,

$$s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \dots \xrightarrow{w_n} s_n \quad (4)$$

iff

$$(s_0, \Lambda_0, \alpha_0) \xrightarrow{w_1} (s_1, \Lambda_1, \alpha_1) \xrightarrow{w_2} \dots \xrightarrow{w_n} (s_n, \Lambda_n, \alpha_n) \text{ for some } \Lambda_i \text{ and } \alpha_i \quad (5)$$

by definition. Note that this notation is *essentially ambiguous* if we divide this as a composition of relations; i.e., given

$$s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \dots \xrightarrow{w_i} s_i \quad \text{and} \quad s_i \xrightarrow{w_{i+1}} s_{i+1} \xrightarrow{w_{i+2}} \dots \xrightarrow{w_n} s_n \quad (6)$$

(4) (namely (5)) does not necessarily hold, (although the converse always holds). Throughout this paper, when we write (4), this always means (5), and does not mean (6) for any i , except the case where the ambiguity can be avoided by Lemma 17 - (iv), (v) below.

Lemma 17. (i) $s \xrightarrow{\langle \sigma \rangle} s'$ iff $s \xrightarrow{\langle \sigma \rangle_p} s'$ for some (unique) $p \in P$.

(ii) If $s \xrightarrow{\langle \sigma \rangle} s_i$ ($i = 1, 2$), then $s_1 = s_2$. Also, for a well-matched nested word w , if $(s, \Lambda_i, \alpha_i) \xrightarrow{w} (s'_i, \Lambda'_i, \alpha'_i)$ ($i = 1, 2$), then $s'_1 = s'_2$ and $\Lambda_i = \Lambda'_i$ for each $i = 1, 2$. Especially, if $w_1 \dots w_n = w'_1 \dots w'_n$ is a well-matched nested word and if $s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \dots \xrightarrow{w_n} s_n$ and $s_0 \xrightarrow{w'_1} s'_1 \xrightarrow{w'_2} \dots \xrightarrow{w'_n} s'_n$, then $s_n = s'_n$.

(iii) If $w_1 \cdots w_n$ is a well-matched nested word and $s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n$, then for any Λ_0 and α_0 , there exist $\Lambda_1, \dots, \Lambda_{n-1}$ and $\alpha_1, \dots, \alpha_n$ such that

$$(s_0, \Lambda_0, \alpha_0) \xrightarrow{w_1} (s_1, \Lambda_1, \alpha_1) \xrightarrow{w_2} \cdots \xrightarrow{w_{n-1}} (s_{n-1}, \Lambda_{n-1}, \alpha_{n-1}) \xrightarrow{w_n} (s_n, \Lambda_0, \alpha_n).$$

(iv) Let w be a well-matched nested word. Then,

$$\begin{aligned} & s \xrightarrow{\langle \sigma \rangle} s_0 \quad \text{and} \quad s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \\ \text{iff} \quad & s \xrightarrow{\langle \sigma \rangle_p} s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \xrightarrow{\langle \sigma \rangle_p} s' \quad \text{for some (unique) } p, s' \\ \text{iff} \quad & s \xrightarrow{\langle \sigma \rangle} s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \\ \text{iff} \quad & s \xrightarrow{\langle \sigma \rangle} s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \xrightarrow{\langle \sigma \rangle} s' \quad \text{for some (unique) } s'. \end{aligned}$$

(v) Let $w_1 \cdots w_n$ and $w'_1 \cdots w'_n$ be well-matched nested words. Then,

$$\begin{aligned} & s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \xrightarrow{w'_1} s'_1 \xrightarrow{w'_2} \cdots \xrightarrow{w'_n} s'_n \\ \text{iff} \quad & s_0 \xrightarrow{w_1} s_1 \xrightarrow{w_2} \cdots \xrightarrow{w_n} s_n \quad \text{and} \quad s_n \xrightarrow{w'_1} s'_1 \xrightarrow{w'_2} \cdots \xrightarrow{w'_n} s'_n \end{aligned}$$

Proof. (i) Clear.

(ii) The first one is clear by (i). The second one can be shown by induction on w , and the last one immediately follows from the second one.

(iii) This follows immediately from (ii) since δ^* is always defined for well-matched nested words.

(iv) The first “iff” is obvious by (i). The second “iff” follows from (iii). The last “iff” is obvious since δ^* is always defined for well-matched nested words.

(v) This follows from (iii).

Lemma 18. (i) For any $t = \sigma(t_1, \dots, t_n)$ and $\pi \in \Pi$, if $t \in \mathcal{L}(\pi)$ then $\pi = (s^c, \sigma, s^r)$ for some s^c, s^r .

(ii) For $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$ and $s^c, s^r \in S$, there exists a transition $s^c \xrightarrow{\langle \sigma \rangle} s_1 \xrightarrow{[t_1] \cdots [t_n]} s^r \xrightarrow{\langle \sigma \rangle} s'$ iff $(s^c, \sigma, s^r) \in \Pi$ and $t \in \mathcal{L}((s^c, \sigma, s^r))$.

(iii) For any $\pi \in \Pi$, $\mathcal{L}(\pi) \neq \emptyset$.

Proof. For any $t = \sigma(t_1, \dots, t_n)$ and $\pi \in \Pi$, by the definition of NBTA and θ ,

$$\begin{aligned} & t \in \mathcal{L}(\pi) \\ \iff & \\ & \pi \in \theta(\sigma, (\pi_1, \dots, \pi_n)), t_1 \in \mathcal{L}(\pi_1), \dots, t_n \in \mathcal{L}(\pi_n) \text{ for some } \pi_1, \dots, \pi_n \in \Pi \\ \iff & \\ & \pi = (s^c, \sigma, s^r), \text{vst}((s^c, \sigma, s^r), \pi_1, \dots, \pi_n), t_1 \in \mathcal{L}(\pi_1), \dots, t_n \in \mathcal{L}(\pi_n) \\ & \text{for some } s^c, s^r \in S \text{ and } \pi_1, \dots, \pi_n \in \Pi. \end{aligned}$$

This proves the item (i) and is used below. We now prove the item (ii) by induction on t .

The “if” part: Let $t \in \mathcal{L}((s^c, \sigma, s^r))$; then $\text{vst}((s^c, \sigma, s^r), \pi_1, \dots, \pi_n)$ and $t_i \in \mathcal{L}(\pi_i)$ for some $\pi_1, \dots, \pi_n \in \Pi$. By the vst condition, for some $s'_1, \dots, s'_n \in S$ and $p, p_1, \dots, p_n \in P$ we have a transition:

$$s^c \xrightarrow{p} s_1 \xrightarrow{p_1} s'_1, \quad s'_1 \xrightarrow{p_1} s_2 \xrightarrow{p_2} s'_2, \quad s'_2 \xrightarrow{p_2} s_3 \cdots \\ \cdots s_n \xrightarrow{p_n} s'_n, \quad s'_n \xrightarrow{p_n} s^r$$

where s_i and s_i^r are the first and third components of π_i , respectively. Let $t_i = \sigma_i(t_1^i, \dots, t_{l_i}^i)$. Since $t_i \in \mathcal{L}(\pi_i) = \mathcal{L}((s_i, \sigma_i, s_i^r))$, by induction hypothesis, for each i there exists s_i'' and transitions:

$$s_i \xrightarrow{\langle \sigma_i \rangle} s_i'' \quad \text{and} \quad s_i'' \xrightarrow{\langle [t_1^i] \cdots [t_{l_i}^i] \rangle} s_i^r.$$

Since $\xrightarrow{\langle \sigma_i \rangle}$ is deterministic, $s'_i = s_i''$. Thus we have obtained

$$s^c \xrightarrow{p} s_1 \xrightarrow{p_1} s'_1 \xrightarrow{\langle [t_1^1] \cdots [t_{l_1}^1] \rangle} s_1^r \xrightarrow{p_1} s_2 \xrightarrow{p_2} s'_2 \xrightarrow{\langle [t_1^2] \cdots [t_{l_2}^2] \rangle} s_2^r \xrightarrow{p_2} s_3 \cdots \\ \cdots s_n \xrightarrow{p_n} s'_n \xrightarrow{\langle [t_1^n] \cdots [t_{l_n}^n] \rangle} s_n^r \xrightarrow{p_n} s^r$$

and hence by Lemma 17 - (iv), (v), we have

$$s^c \xrightarrow{s_1} s^r \xrightarrow{\langle [t_1] \cdots [t_n] \rangle} s^r \xrightarrow{s'} s'.$$

The “only if” part just proceeds in the converse way to the above.

The item (iii) is clear from the above argument; π contains the root symbol of the required tree and the definition of Π (and Π_i) ensures the existence of some “child” states π_1, \dots, π_n , recursively. In fact we can show by induction on i that, for any $i \in \mathbb{N}$ and any $\pi \in \Pi_i$ there is a tree $t \in \mathcal{L}(\pi)$ whose height is at most i . \square

Remark 19. Above, the item (iii) ensures that all the states of the NBTA A generate non-empty regular languages, as required always in the current paper. If we change the definition of Π to $\Pi \triangleq S \times \Sigma \times S$, still we obtain an NBTA and the item (ii) holds; the current definition of Π is nothing but the set of states $\pi \in S \times \Sigma \times S$ such that $\mathcal{L}(\pi) \neq \emptyset$.

Remark 20. Our construction of the NBTA A from the state-transitions δ_c, δ_r of T given in Section 4.2 and that of the state-transitions δ_c, δ_r of T from a DBTA A given in Section 4.1 are basically similar to the construction given in [2] except for the design of a state $\pi = (s^c, \sigma, s^r)$ in our constructions of the NBTA A : (i) Our style of a state π contains the information of σ , which is used in the definition of rules of T . (ii) We use s^r , which is a state *before* a return-transition δ_r while the construction in [2] uses a state *after* a return-transition δ_r . Since δ_r is a function, our information is “richer” than the other (i.e., given s^r , we can obtain “a state *after* a return-transition” simply as $\delta_r(s^r, p, \sigma)$), and we use s^r as an argument of ρ_r in the definitions of rules and $Init$ of T .

Lemma 21. *For $s^c \in S$ and $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$, there exists exact one state $s^r \in S$ such that $(s^c, \sigma, s^r) \in \Pi$ and $t \in \mathcal{L}((s^c, \sigma, s^r))$.*

Proof. The uniqueness follows from Lemma 18 - (ii) and Lemma 17 - (ii). The existence also follows from Lemma 18 - (ii) since δ^* is always defined for well-matched nested words. \square

Lemma 22. *For $(s^c, \sigma, s^r) \in \Pi$, $t \in \mathcal{L}((s^c, \sigma, s^r))$, and $\gamma \in \Gamma$, $\llbracket (s^c, s^r, \gamma) \rrbracket_M(t)$ is always defined. Hence, for any $(\tau, \pi) \in \text{Init}$ and $t \in \mathcal{L}(\pi)$, $\llbracket \tau \rrbracket_M(t)$ is always defined.*

Proof. The latter follows immediately from the former. We prove the former by induction on t .

Let $t = \sigma(t_1, \dots, t_n)$. Since $t \in \mathcal{L}((s^c, \sigma, s^r))$, there exist $\pi_i = (s_i^c, \sigma_i, s_i^r) \in \Pi$ ($i = 1, \dots, n$) such that: $(s^c, \sigma, s^r) \in \theta(\sigma, (\pi_1, \dots, \pi_n))$; $t_i \in \mathcal{L}(\pi_i)$ for each $i = 1, \dots, n$; and $\text{vst}((s^c, \sigma, s^r), (\pi_1, \dots, \pi_n))$ holds. Then by the definition of R , there exists $\tau \triangleq \text{rhs}((s^c, s^r, \gamma), \sigma, (\pi_1, \dots, \pi_n))$, and $\llbracket (s^c, s^r, \gamma) \rrbracket_M(t) = \llbracket \tau \rrbracket_M(t_1, \dots, t_n)$ if $\llbracket \tau \rrbracket_M(t_1, \dots, t_n)$ is defined. Recall the definition of τ after (3) in the proof of Lemma 7. In τ , an occurrence of an element in $Q(X_n)$ is of the form $(s_i^c, s_i^r, \gamma')(x_i)$ —given in η_i —for some $\gamma' \in \Gamma$, and then $\llbracket \tau \rrbracket_M(t_1, \dots, t_n)$ involves $\llbracket (s_i^c, s_i^r, \gamma') \rrbracket_M(t_i)$, which is defined by induction hypothesis. Thus $\llbracket \tau \rrbracket_M(t_1, \dots, t_n)$ is defined, and so is $\llbracket (s^c, s^r, \gamma) \rrbracket_M(t)$. \square

Lemma 23. *The domain of M is isomorphic to the domain of T by $[-]$.*

Proof. Let $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$. It holds that

$$\begin{aligned} & \langle \sigma [t_1] \cdots [t_n] \sigma \rangle \in \text{Dom}(T) \\ \iff & (s_0, \varepsilon, \alpha_\varepsilon) \xrightarrow{\langle \sigma \rangle} (s_1, (p_1, \alpha_1), \alpha_\varepsilon) \xrightarrow{[t_1] \cdots [t_n]} (s^r, (p_1, \alpha_1), \alpha) \xrightarrow{\langle \sigma \rangle} (s', \varepsilon, \alpha') \\ & \wedge s' \in \text{Dom}(F) \quad \text{where } s_1, p_1, \alpha_1, s^r, \alpha, s', \alpha' \text{ are given by the transitions} \\ & \hspace{15em} \text{(by the definition of } \llbracket T \rrbracket \text{)} \\ \iff & (\tau, (s_0, \sigma, s^r)) \in \text{Init} \wedge t \in \mathcal{L}((s_0, \sigma, s^r)) \quad \text{for some } \tau, s^r \\ & \hspace{15em} \text{(by the definition of } \text{Init}, \text{ Lemma 18 - (ii), and Lemma 17 - (iii))} \\ \iff & (\tau, (s^c, \sigma', s^r)) \in \text{Init} \wedge t \in \mathcal{L}((s^c, \sigma', s^r)) \wedge \llbracket \tau \rrbracket_M(t) \text{ is defined} \\ & \hspace{15em} \text{for some } \tau, s^c, \sigma', s^r \\ & \hspace{15em} \text{(by Lemma 22, the definition of } \text{Init}, \text{ and Lemma 18-(i))} \\ \iff & t \in \text{Dom}(M). \hspace{15em} \text{(by the definitions of } \llbracket M \rrbracket \text{ and } \text{Init}) \end{aligned}$$

\square

Lemma 24. *M is well-defined as a yDT^R : i.e.,*

- (i) *for any $(\tau, \pi), (\tau', \pi') \in \text{Init}$, if $(\tau, \mathcal{L}(\pi)) \neq (\tau', \mathcal{L}(\pi'))$, then $\mathcal{L}(\pi) \cap \mathcal{L}(\pi') = \emptyset$,*
- (ii) *for any $(q, \sigma, \tau, (\pi_1, \dots, \pi_n)), (q, \sigma, \tau', (\pi'_1, \dots, \pi'_n)) \in R$, if*

$$(q, \sigma, \tau, (\mathcal{L}(\pi_1), \dots, \mathcal{L}(\pi_n))) \neq (q, \sigma, \tau', (\mathcal{L}(\pi'_1), \dots, \mathcal{L}(\pi'_n)))$$

then $\mathcal{L}(\pi_i) \cap \mathcal{L}(\pi'_i) = \emptyset$ for some $i \in [n]$.

Proof. On (i): Let us assume that there exists $t = \sigma(t_1, \dots, t_n) \in \mathcal{L}(\pi) \cap \mathcal{L}(\pi')$ and show the contradiction. Since $t \in \mathcal{L}(\pi) \cap \mathcal{L}(\pi')$ and $(\tau, \pi), (\tau', \pi') \in \text{Init}$, each of π and π' is of the form (s_0, σ, s) . By Lemma 21 there exists exactly one state of the form $(s_0, \sigma, s) \in \Pi$ such that $t \in \mathcal{L}((s_0, \sigma, s))$. Hence $\pi = \pi'$. Then $\tau = \tau'$ by the definition of *Init*, which contradicts $(\tau, \mathcal{L}(\pi)) \neq (\tau', \mathcal{L}(\pi'))$.

On (ii): Let us assume that there exists $t_i \in \mathcal{L}(\pi_i) \cap \mathcal{L}(\pi'_i)$ for each $i \in [n]$, and show the contradiction. First note that we have $\pi_i \neq \pi'_i$ for some $i \in [n]$ —since otherwise by the definition of R we have $\tau = \tau'$, which contradicts the assumption—and let i_0 be the least such i ; thus $\pi_{i_0} \neq \pi'_{i_0}$ and $\pi_i = \pi'_i$ for $i < i_0$. Let $\pi_i = (s_i^c, \sigma_i, s_i^r)$, $\pi'_i = (s_i^{c'}, \sigma_i, s_i^{r'})$, and $t_i = \sigma_i(t_1^i, \dots, t_n^i)$, for each $i = 1, \dots, n$, and $q = (s^c, s^r, \gamma)$. By the definition of R , $\text{vst}((s^c, \sigma, s^r), \pi_1, \dots, \pi_n)$ and $\text{vst}((s^c, \sigma, s^r), \pi'_1, \dots, \pi'_n)$ hold, and also we have $\pi_i = \pi'_i \in \mathcal{L}(t_i)$ for $i < i_0$ with Lemma 18 - (ii); therefore, we have

$$s^c \xrightarrow{\langle \sigma \rangle} s_1^c \xrightarrow{[t_1]} s_2^c \xrightarrow{[t_2]} \dots s_{i_0-1}^c \xrightarrow{[t_{i_0-1}]} s_{i_0}^c \xrightarrow{\langle \sigma_{i_0} [t_1^{i_0}] \dots [t_{i_0}^{i_0}] \rangle} s_{i_0}^r$$

and

$$s^c \xrightarrow{\langle \sigma \rangle} s_1^c \xrightarrow{[t_1]} s_2^c \xrightarrow{[t_2]} \dots s_{i_0-1}^c \xrightarrow{[t_{i_0-1}]} s_{i_0}^{c'} \xrightarrow{\langle \sigma_{i_0} [t_1^{i_0}] \dots [t_{i_0}^{i_0}] \rangle} s_{i_0}^{r'}.$$

Note that the above two sequences start from the same state s^c even if $i_0 = 1$. Hence, by using Lemma 17 - (ii) twice for $\langle \sigma \rangle$ and for $[t_1] \dots [t_{i_0-1}]$, we obtain $s_{i_0}^c = s_{i_0}^{c'}$, and then similarly we obtain $s_{i_0}^r = s_{i_0}^{r'}$, which contradicts $\pi_{i_0} \neq \pi'_{i_0}$. \square

We extend $\llbracket - \rrbracket_M$ to $\mathcal{A}(\Gamma, Q(X_n), \Delta)$: for $\rho \in \mathcal{A}(\Gamma, Q(X_n), \Delta)$ and $t_1, \dots, t_n \in \mathcal{T}_\Sigma$, we define

$$\llbracket \rho \rrbracket_M(t_1, \dots, t_n) \triangleq [\gamma := \llbracket \rho(\gamma) \rrbracket_M(t_1, \dots, t_n)]_{\gamma \in \Gamma} \in \mathcal{A}(\Gamma, \emptyset, \Delta)$$

if $\llbracket \rho(\gamma) \rrbracket_M(t_1, \dots, t_n)$ is defined for every $\gamma \in \Gamma$, and $\llbracket \rho \rrbracket_M(t_1, \dots, t_n)$ is not defined otherwise.

Lemma 25. (i) For $e \in E(\Gamma, \Delta)$, $\alpha \in \mathcal{A}(\Gamma', \Gamma, \Delta)$, $\rho \in \mathcal{A}(\Gamma, Q(X_n), \Delta)$ and $t_1, \dots, t_n \in \mathcal{T}_\Sigma$, if $\llbracket \rho \rrbracket_M(t_1, \dots, t_n)$ is defined, then so are $\llbracket e\rho \rrbracket_M(t_1, \dots, t_n)$ and $\llbracket \alpha\rho \rrbracket_M(t_1, \dots, t_n)$, and

$$\begin{aligned} \llbracket e\rho \rrbracket_M(t_1, \dots, t_n) &= e \llbracket \rho \rrbracket_M(t_1, \dots, t_n) \in \Delta^* \\ \llbracket \alpha\rho \rrbracket_M(t_1, \dots, t_n) &= \alpha \llbracket \rho \rrbracket_M(t_1, \dots, t_n) \in \Delta^*. \end{aligned}$$

(ii) For $\rho_i \in \mathcal{A}(\Gamma_i, Q(X_n), \Delta)$ ($i = 1, 2$) such that $\Gamma_1 \cap \Gamma_2 = \emptyset$ holds, and for $t_1, \dots, t_n \in \mathcal{T}_\Sigma$, if $\llbracket \rho_1 \rrbracket_M(t_1, \dots, t_n)$ and $\llbracket \rho_2 \rrbracket_M(t_1, \dots, t_n)$ are defined, then so is $\llbracket \rho_1 \uplus \rho_2 \rrbracket_M(t_1, \dots, t_n)$, and

$$\llbracket \rho_1 \uplus \rho_2 \rrbracket_M(t_1, \dots, t_n) = \llbracket \rho_1 \rrbracket_M(t_1, \dots, t_n) \uplus \llbracket \rho_2 \rrbracket_M(t_1, \dots, t_n).$$

Proof. (i) By induction on e and α , respectively.

(ii) By case analysis on an argument $\gamma \in \Gamma_1 \uplus \Gamma_2$.

Lemma 26. For $t = \sigma(t_1, \dots, t_n) \in \mathcal{T}_\Sigma$, if

$$(s^c, \Lambda, \alpha) \xrightarrow{\langle \sigma [t_1] \dots [t_n] \rangle} (s^r, (p, \alpha')\Lambda, \alpha^r)$$

then $\llbracket (s^c, s^r, \gamma) \rrbracket_M(t) = \alpha^r(\gamma)$ for every $\gamma \in \Gamma$. \square

Proof. The proof proceeds by induction on t .

Let $t_i = \sigma_i(t_1^i, \dots, t_{l_i}^i)$ and suppose that we have

$$\begin{aligned} (s^c, \Lambda, \alpha) &\xrightarrow{\langle \sigma \rangle} (s_1^c, \Lambda_1, \alpha_1) \xrightarrow{\langle \sigma_1 [t_1^1] \dots [t_{l_1}^1] \rangle} (s_1^r, (p_1, \alpha'_1)\Lambda_1, \alpha_1^r) \xrightarrow{\langle \sigma_1 \rangle} \\ &(s_2^c, \Lambda_2, \alpha_2) \xrightarrow{\langle \sigma_2 [t_1^2] \dots [t_{l_2}^2] \rangle} (s_2^r, (p_2, \alpha'_2)\Lambda_2, \alpha_2^r) \xrightarrow{\langle \sigma_2 \rangle} \\ &\quad \vdots \\ &(s_n^c, \Lambda_n, \alpha_n) \xrightarrow{\langle \sigma_n [t_1^n] \dots [t_{l_n}^n] \rangle} (s_n^r, (p_n, \alpha'_n)\Lambda_n, \alpha_n^r) \xrightarrow{\langle \sigma_n \rangle} (s^r, (p, \alpha')\Lambda, \alpha^r). \end{aligned}$$

Then we have

$$\begin{aligned} \alpha_1 &= \alpha_\varepsilon^\Gamma \\ \alpha'_i &= \rho_c(s_i^c, \sigma_i)\alpha_i \\ \overline{\alpha'_i} &= \overline{\rho_c(s_i^c, \sigma_i)\alpha_i} = \overline{\rho_c(s_i^c, \sigma_i)}\alpha_i = \beta_i^c\alpha_i \end{aligned}$$

and hence, by the definition of T -transition,

$$\begin{aligned} \alpha^r &= \rho_r(s_n^r, p_n, \sigma_n)(\alpha_n^r \uplus \overline{\alpha'_n}) \\ &= \beta_n^r(\alpha_n^r \uplus (\beta_n^c\alpha_n)) \\ &= \beta_n^r(\alpha_n^r \uplus (\beta_n^c(\rho_r(s_{n-1}^r, p_{n-1}, \sigma_{n-1})(\alpha_{n-1}^r \uplus \overline{\alpha'_{n-1}})))) \\ &= \beta_n^r(\alpha_n^r \uplus (\beta_n^c(\beta_{n-1}^r(\alpha_{n-1}^r \uplus (\beta_{n-1}^c\alpha_{n-1})))) \\ &= \dots \\ &= \beta_n^r(\alpha_n^r \uplus (\beta_n^c(\dots(\beta_1^r(\alpha_1^r \uplus (\beta_1^c\alpha_1))\dots))) \\ &= \beta_n^r(\alpha_n^r \uplus (\beta_n^c(\dots(\beta_1^r(\alpha_1^r \uplus (\beta_1^c\alpha_\varepsilon^\Gamma))\dots))). \end{aligned}$$

Let $\pi_i \triangleq (s_i^c, \sigma_i, s_i^r)$. By Lemma 18 - (ii),

$$t_i \in \mathcal{L}(\pi_i). \quad (7)$$

Also, on (3) in the proof of Lemma 7, recall that

$$\eta_i \triangleq [\gamma := (s_i^c, s_i^r, \gamma)(x_i)]_{\gamma \in \Gamma} \in \mathcal{A}(\Gamma, Q(X_n), \Delta).$$

By induction hypothesis, $\llbracket \eta_i \rrbracket_M(t_1, \dots, t_n)$ is defined and

$$\llbracket \eta_i \rrbracket_M(t_1, \dots, t_n) = \alpha_i^r. \quad (8)$$

Then, for each $\gamma \in \Gamma$,

$$\begin{aligned}
& \llbracket (s^c, s^r, \gamma) \rrbracket_M(t) \\
&= \llbracket \text{rhs}((s^c, s^r, \gamma), \sigma, (\pi_1, \dots, \pi_n)) \rrbracket_M(t_1, \dots, t_n) && \text{(by (7))} \\
&= \llbracket \gamma \left(\beta_n^r (\eta_n \uplus (\beta_n^c (\dots (\beta_1^r (\eta_1 \uplus (\beta_1^c \alpha_\varepsilon^\Gamma)) \dots))) \right) \rrbracket_M(t_1, \dots, t_n) \\
&= \gamma \left(\beta_n^r (\alpha_n^r \uplus (\beta_n^c (\dots (\beta_1^r (\alpha_1^r \uplus (\beta_1^c \alpha_\varepsilon^\Gamma)) \dots))) \right) \\
&\hspace{15em} \text{(by Lemma 25, (8), and } \llbracket \alpha_\varepsilon^\Gamma \rrbracket_M(t_1, \dots, t_n) = \alpha_\varepsilon^\Gamma) \\
&= \alpha^r(\gamma). \hspace{15em} \square
\end{aligned}$$

Lemma 27. $\llbracket M \rrbracket(\lceil w \rceil) = \llbracket T \rrbracket(w)$ for every $w \in \text{Dom}(T)$.

Proof. Let $t = \sigma(t_1, \dots, t_n) = \lceil w \rceil \in \text{Dom}(M) = \lceil \text{Dom}(T) \rceil$, and let the transition by $\lfloor t \rfloor$ be

$$(s_0, \varepsilon, \alpha_\varepsilon^\Gamma) \xrightarrow{\langle \sigma \lfloor t_1 \rfloor \dots \lfloor t_n \rfloor \rangle} (s^r, (p, \rho_c(s_0, \sigma) \alpha_\varepsilon^\Gamma), \alpha^r) \xrightarrow{\sigma} (s', \varepsilon, \alpha').$$

By Lemma 18 - (ii), $t \in \mathcal{L}((s_0, \sigma, s^r))$. Since $t \in \text{Dom}(M)$, we have:

$$\begin{aligned}
& \llbracket M \rrbracket(t) \\
&= \llbracket \text{Init}((s_0, \sigma, s^r)) \rrbracket_M(t) \\
&= \llbracket F(s') \beta_{s^r, p, \sigma}^r (\eta_{s^r} \uplus (\beta_\sigma^c \alpha_\varepsilon^\Gamma)) \rrbracket_M(t) \\
&= F(s') \beta_{s^r, p, \sigma}^r (\llbracket \eta_{s^r} \rrbracket_M(t) \uplus (\beta_\sigma^c \alpha_\varepsilon^\Gamma)) && \text{(by Lemma 25 and } \llbracket \alpha_\varepsilon^\Gamma \rrbracket_M(t) = \alpha_\varepsilon^\Gamma) \\
&= F(s') \beta_{s^r, p, \sigma}^r (\alpha^r \uplus (\beta_\sigma^c \alpha_\varepsilon^\Gamma)) && \text{(by Lemma 26)} \\
&= F(s') \rho_r(s^r, p, \sigma) (\alpha^r \uplus \overline{\rho_c(s_0, \sigma) \alpha_\varepsilon^\Gamma}).
\end{aligned}$$

On the other hand, by the definition of T -transition, we have

$$\begin{aligned}
\llbracket T \rrbracket(w) &= F(s') \alpha' \\
&= F(s') \rho_r(s^r, p, \sigma) (\alpha^r \uplus \overline{\rho_c(s_0, \sigma) \alpha_\varepsilon^\Gamma}) \\
&= F(s') \rho_r(s^r, p, \sigma) (\alpha^r \uplus \overline{\rho_c(s_0, \sigma) \alpha_\varepsilon^\Gamma}) \\
&= \llbracket M \rrbracket(t). \hspace{15em} \square
\end{aligned}$$

D Examples

The following yDT^R is semantically equivalent to the SRTST in Example 5.

Example 28. Let us consider a DBTA $A \triangleq (II, \Sigma, \theta)$ where $\Sigma \triangleq \{\mathbf{f}^{(2)}, \mathbf{a}^{(0)}, \mathbf{b}^{(0)}\}$, $II \triangleq \{\pi_{\mathbf{a}}, \pi_{\mathbf{b}}\}$, and θ is defined by

$$\theta(\mathbf{f}, (\pi, \pi')) \triangleq \{\pi\} \text{ for } \pi, \pi' \in II, \quad \theta(\mathbf{a}, ()) \triangleq \{\pi_{\mathbf{a}}\}, \quad \theta(\mathbf{b}, ()) \triangleq \{\pi_{\mathbf{b}}\}.$$

For $d \in \{\mathbf{a}, \mathbf{b}\}$, π_d accepts just a tree whose leftmost leaf is d .

With this regular look-ahead automaton A , let us consider a yDT^{R} $M \triangleq (Q, \Sigma, \Delta, \text{Init}, R)$ where

$$Q \triangleq \{q\}, \quad \Delta \triangleq \{\mathbf{a}, \mathbf{b}\}, \quad \text{Init} \triangleq \{(q(x_1), \pi_{\mathbf{a}}), (q(x_1), \pi_{\mathbf{b}})\}$$

and the set of rules R are:

$$\begin{aligned} q(\mathbf{f}(x_1, x_2)) &\rightarrow q(x_1)q(x_2) \quad \langle \pi_{\mathbf{a}}, \pi_d \rangle, & q(d) &\rightarrow d, \\ q(\mathbf{f}(x_1, x_2)) &\rightarrow q(x_2)q(x_1) \quad \langle \pi_{\mathbf{b}}, \pi_d \rangle, & (d \in \{\mathbf{a}, \mathbf{b}\}). \end{aligned}$$

The rules are self-explanatory: given $t \in \mathcal{T}_{\Sigma}$, $\llbracket M \rrbracket = \llbracket q \rrbracket_M$ recursively swaps the two subtrees of the root if the leftmost leaf is \mathbf{b} , and skip the swapping otherwise; and then produces the leaves as the output. For instance,

$$\begin{aligned} \llbracket M \rrbracket(\mathbf{f}(\mathbf{f}(\mathbf{b}, \mathbf{a}), \mathbf{f}(\mathbf{a}, \mathbf{b}))) &= \llbracket q \rrbracket_M(\mathbf{f}(\mathbf{f}(\mathbf{b}, \mathbf{a}), \mathbf{f}(\mathbf{a}, \mathbf{b}))) \\ &= \llbracket q \rrbracket_M(\mathbf{f}(\mathbf{a}, \mathbf{b}))\llbracket q \rrbracket_M(\mathbf{f}(\mathbf{b}, \mathbf{a})) = \llbracket q \rrbracket_M(\mathbf{a})\llbracket q \rrbracket_M(\mathbf{b})\llbracket q \rrbracket_M(\mathbf{a})\llbracket q \rrbracket_M(\mathbf{b}) = \mathbf{abab}. \end{aligned}$$

Example 29. By applying the construction in the proof of Lemma 6 to the yDT^{R} in Example 28, we obtain an SRTST $T = (S, \Sigma, \Delta, P, s_0, \Gamma, F, \delta_c, \delta_r, \rho_c, \rho_r)$ as follows. Recall that $\Sigma = \{\mathbf{f}^{(2)}, \mathbf{a}^{(0)}, \mathbf{b}^{(0)}\}$ and $\Delta = \{\mathbf{a}, \mathbf{b}\}$.

The set S of states, the set P of stack symbols and the set Γ of variables are defined by

$$\begin{aligned} S &\triangleq \{(), (\pi_{\mathbf{a}}), (\pi_{\mathbf{b}}), (\pi_{\mathbf{a}}, \pi_{\mathbf{a}}), (\pi_{\mathbf{a}}, \pi_{\mathbf{b}}), (\pi_{\mathbf{b}}, \pi_{\mathbf{b}}), (\pi_{\mathbf{b}}, \pi_{\mathbf{a}})\} = \Pi^{(\leq 2)}, \\ P &\triangleq \{(), (\pi_{\mathbf{a}}), (\pi_{\mathbf{b}}), (\pi_{\mathbf{a}}, \pi_{\mathbf{a}}), (\pi_{\mathbf{a}}, \pi_{\mathbf{b}}), (\pi_{\mathbf{b}}, \pi_{\mathbf{b}}), (\pi_{\mathbf{b}}, \pi_{\mathbf{a}})\} = \Pi^{(\leq 2)}, \\ \Gamma &\triangleq \{q(x_1), q(x_2)\} = Q(X_2), \end{aligned}$$

and $s_0 \triangleq ()$. Also, $F((\pi_{\mathbf{a}})) \triangleq q(x_1)$ and $F((\pi_{\mathbf{b}})) \triangleq q(x_1)$. The call state-transition function δ_c is:

$$\delta_c((), \sigma) \triangleq ((), ()), \quad \delta_c((\pi_d), \sigma) \triangleq ((), (\pi_d))$$

for every $d \in \{\mathbf{a}, \mathbf{b}\}$. The return state-transition function δ_r is defined by

$$\begin{aligned} \delta_r((), (), d_1) &\triangleq (\pi_{d_1}), \\ \delta_r((\pi_{d_1}, \pi), (), \mathbf{f}) &\triangleq (\pi_{d_1}), \\ \delta_r((), (\pi_{d_1}), d_2) &\triangleq (\pi_{d_1}, \pi_{d_2}), \\ \delta_r((\pi_{d_2}, \pi), (\pi_{d_1}), \mathbf{f}) &\triangleq (\pi_{d_1}, \pi_{d_2}) \end{aligned}$$

for every $\pi \in \Pi$ and $d_1, d_2 \in \{\mathbf{a}, \mathbf{b}\}$. The call variable-update function ρ_c is defined by

$$\rho_c(s, \sigma) \triangleq [\gamma := \gamma]_{\gamma \in \Gamma}.$$

The return variable-update function ρ_r is defined as follows:

$$\begin{aligned} \rho_r((s, \mathbf{a}), (s, \mathbf{a}), d) &\triangleq [q(x_1) := d], \\ \rho_r((s, \mathbf{a}), (\pi_1), d) &\triangleq [q(x_1) := \overline{q(x_1)}, q(x_2) := d], \\ \rho_r((\pi_a, \pi_1), (s, \mathbf{f}), \mathbf{f}) &\triangleq [q(x_1) := q(x_1)q(x_2)], \\ \rho_r((\pi_b, \pi_1), (s, \mathbf{f}), \mathbf{f}) &\triangleq [q(x_1) := q(x_2)q(x_1)], \\ \rho_r((\pi_a, \pi_1), (\pi_2), \mathbf{f}) &\triangleq [q(x_1) := \overline{q(x_1)}, q(x_2) := q(x_1)q(x_2)], \\ \rho_r((\pi_b, \pi_1), (\pi_2), \mathbf{f}) &\triangleq [q(x_1) := \overline{q(x_1)}, q(x_2) := q(x_2)q(x_1)]. \end{aligned}$$

for every $\pi_1, \pi_2 \in \Pi$ and $d \in \{\mathbf{a}, \mathbf{b}\}$.

Example 30. By applying the construction in the proof of Lemma 7 to the SRTST in Example 5, we obtain a yDT^R $M = (Q, \Sigma, \Delta, Init, R)$ with a DBTA $A = (\Pi, \Sigma, \theta)$ as follows. Recall that $\Sigma = \{\mathbf{f}^{(2)}, \mathbf{a}^{(0)}, \mathbf{b}^{(0)}\}$ and $\Delta = \{\mathbf{a}, \mathbf{b}\}$.

The set Π of states is obtained as below:

$$\begin{aligned} \Pi_0 &= \{(s?, \mathbf{a}, s?), (s?, \mathbf{b}, s?), (s_a, \mathbf{a}, s?), (s_a, \mathbf{b}, s?), (s_b, \mathbf{a}, s?), (s_b, \mathbf{b}, s?)\}, \\ \Pi_1 &= \Pi_0 \cup \{(s?, \mathbf{f}, s_a), (s?, \mathbf{f}, s_b), (s_a, \mathbf{f}, s_a), (s_a, \mathbf{f}, s_b), (s_b, \mathbf{f}, s_a), (s_b, \mathbf{f}, s_b)\}, \\ \Pi_2 &= \Pi_1 \cup \{(s?, \mathbf{f}, s_a), (s?, \mathbf{f}, s_b), (s_a, \mathbf{f}, s_a), (s_a, \mathbf{f}, s_b), (s_b, \mathbf{f}, s_a), (s_b, \mathbf{f}, s_b)\} \\ &= \Pi_1. \end{aligned}$$

So we use Π_2 as Π . The transition function θ is defined as follows:

$$\begin{aligned} \theta(d_1) &\triangleq \{(s?, d_1, s?), (s_a, d_1, s?), (s_b, d_1, s?)\}, \\ \theta(\mathbf{f}, (s?, d_1, s?), (s_{d_1}, d_2, s?)) &\triangleq \{(s?, \mathbf{f}, s_{d_1}), (s_a, \mathbf{f}, s_{d_1}), (s_b, \mathbf{f}, s_{d_1})\}, \\ \theta(\mathbf{f}, (s?, \mathbf{f}, s_{d_1}), (s_{d_1}, d_2, s?)) &\triangleq \{(s?, \mathbf{f}, s_{d_1}), (s_a, \mathbf{f}, s_{d_1}), (s_b, \mathbf{f}, s_{d_1})\}, \\ \theta(\mathbf{f}, (s?, d_1, s?), (s_{d_1}, \mathbf{f}, s_{d_2})) &\triangleq \{(s?, \mathbf{f}, s_{d_1}), (s_a, \mathbf{f}, s_{d_1}), (s_b, \mathbf{f}, s_{d_1})\}, \\ \theta(\mathbf{f}, (s?, \mathbf{f}, s_{d_1}), (s_{d_1}, \mathbf{f}, s_{d_2})) &\triangleq \{(s?, \mathbf{f}, s_{d_1}), (s_a, \mathbf{f}, s_{d_1}), (s_b, \mathbf{f}, s_{d_1})\} \end{aligned}$$

for every $d_1, d_2 \in \{\mathbf{a}, \mathbf{b}\}$. Then

$$Q \triangleq S \times S \times \Gamma = \{s?, s_a, s_b\} \times \{s?, s_a, s_b\} \times \{\gamma\}.$$

The set R of rules consists of the following:

$$\begin{aligned} (s, s_a, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow \mathbf{ad} && \langle (s?, \mathbf{a}, s?), (s_a, d, s?) \rangle \\ (s, s_b, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow \mathbf{db} && \langle (s?, \mathbf{b}, s?), (s_b, d, s?) \rangle \\ (s, s_a, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow (s?, s_a, \gamma)(x_1)d && \langle (s?, \mathbf{f}, s_a), (s_a, d, s?) \rangle \\ (s, s_b, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow d(s?, s_b, \gamma)(x_1) && \langle (s?, \mathbf{f}, s_b), (s_b, d, s?) \rangle \\ (s, s_a, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow (s?, s_a, \gamma)(x_1)(s_a, s_d, \gamma)(x_2) && \langle (s?, \mathbf{f}, s_a), (s_a, \mathbf{f}, s_d) \rangle \\ (s, s_b, \gamma)(\mathbf{f}(x_1, x_2)) &\rightarrow (s_b, s_d, \gamma)(x_2)(s?, s_b, \gamma)(x_1) && \langle (s?, \mathbf{f}, s_b), (s_b, \mathbf{f}, s_d) \rangle \\ (s, s?, \gamma)(d) &\rightarrow \varepsilon && \langle \rangle \end{aligned}$$

for every $s \in S$ and $d \in \{\mathbf{a}, \mathbf{b}\}$. The set *Init* of initial sequences is defined as follows:

$$Init \triangleq \{(d, (s?, d, s?)) \mid d \in \{\mathbf{a}, \mathbf{b}\}\} \cup \{((s?, s_d, \gamma)(x_1), (s?, \mathbf{f}, s_d)) \mid d \in \{\mathbf{a}, \mathbf{b}\}\}.$$