

Refinement Types and Higher-Order Model Checking for Algebraic Effects and Handlers

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This talk is based on the following papers:

1. Fuga Kawamata, Hiroshi Unno, Taro Sekiyama, and Tachio Terauchi. *Answer Refinement Modification: Refinement Type System for Algebraic Effects and Handlers*, POPL 2024.
2. Taro Sekiyama and Hiroshi Unno. *Higher-Order Model Checking of Effect-Handling Programs with Answer-Type Modification*, OOPSLA 2024

Algebraic Effects and Handlers

- A mechanism to structure programs with effects in a modular way
- Can represent many kinds of effects via **delimited continuations**
 - exception, state, I/O, nondeterminism, concurrency, etc. **operation**

```
handle
  Set 1; let a1 = Get () in
  Set 2; let a2 = Get () in
  a1 + a2
with
  | return x    -> λs. x
  | Set v, k    -> λs. k () v
  | Get (), k   -> λs. k s s
```

```
handle
  if Decide () then 1 else 2
with
  | return x    -> x
  | Decide (), k -> k true + k false
```

handler

delimited continuation

- Have been adopted in OCaml 5, etc.

Algebraic Effects and Handlers

● Example

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()

with h handle (Tick (); Tock ())
```

Algebraic Effects and Handlers

● Example

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
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```

delimited continuation



This talk focuses on deep handlers

```
with h handle (Tick (); Tock ())
```

Algebraic Effects and Handlers

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delimited continuation

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`with h handle (Tick (); Tock ())`

$\rightarrow 1 ::$ `with h handle ((); Tock ())`

Algebraic Effects and Handlers

● Example

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let h = handler
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This talk focuses on deep handlers

`with h handle (Tick (); Tock ())`

$\rightarrow 1 :: \text{with h handle } (()); \text{Tock } ()$

$\rightarrow 1 :: \text{with h handle } (\text{Tock } ())$

Algebraic Effects and Handlers

● Example

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let h = handler
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delimited continuation

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with h handle (Tick (); Tock ())

→ 1 :: with h handle ((); Tock ())

→ 1 :: with h handle (Tock ())

Algebraic Effects and Handlers

● Example

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delimited continuation

This talk focuses on deep handlers

with h handle (Tick (); Tock ())

→ 1 :: with h handle (()); Tock ())

→ 1 :: with h handle (Tock ())

→ 1 :: 0 :: with h handle ()

Algebraic Effects and Handlers

● Example

```
let h = handler
  | return x -> []
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This talk focuses on deep handlers

with h handle (Tick (); Tock ())

→ 1 :: with h handle (() ; Tock ())

→ 1 :: with h handle (Tock ())

→ 1 :: 0 :: with h handle ()

Algebraic Effects and Handlers

● Example

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()
```

This talk focuses on deep handlers

```
with h handle (Tick (); Tock ())
```

→ 1 :: with h handle (() ; Tock ())

→ 1 :: with h handle (Tock ())

→ 1 :: 0 :: with h handle ()

→ 1 :: 0 :: []

= [1; 0]

Verification of Programs with Effect Handlers

- Delimited continuations enhance expressivity but introduce complex control flows, posing challenges for program verification
- This talk presents two complementary approaches that addresses the challenges by applying type systems [Danvy+90; Materzok+11] with **Answer Type Modification (ATM)** in different way
 1. Refinement types [Kawamata+ POPL'24]
 - Support functional correctness verification (ongoing extensions to temporal properties)
 - Support infinite data domains (e.g., integers, algebraic data types)
 - Undecidable but automated via Constrained Horn Clause (CHC) solving
 2. Higher-order model checking [Sekiyama and Unno OOPSLA'24]
 - Support modal mu-calculus model checking of effect trees
 - Restricted to finite data domains (e.g., booleans, enum types)
 - Decidable fragment expressible enough to support various effects

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Refinement Types

$$\{x : B \mid \phi\}$$

Formula

Base Type (int, bool etc.)

- Types equipped with predicates
 - E.g. $1 + 2 : \{x : \text{int} \mid x = 3\}$
 $1 + 2 : \{x : \text{int} \mid x > 0\}$
- Often combined with dependent function types $(x : T) \rightarrow C$
 - E.g. $\lambda x. x + 1 : (\textcolor{brown}{x} : \text{int}) \rightarrow \{y : \text{int} \mid y = \textcolor{brown}{x} + 1\}$
- Can represent more specific properties
 - A tool of program verification

Refinement type system for algebraic effect handlers

$\vdash \text{with } h \text{ handle } (\text{Tick } (); \text{Tock } ()) : \{z:\text{int list} \mid z = [1; 0]\}$

- Enables precise verification of algebraic effect handlers
- Can be built on top of existing languages
 - Our implementation for OCaml 5 programs

Challenge

```
let h = handler
| return x -> x
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

The precise types depend on
what effects occur in **what order**

```
with h handle
  (Tick (); Tock ())
(* ==> [1; 0] *)
```

: {z: int list | z = [1; 0]}

```
with h handle
  (Tock (); Tick ())
(* ==> [0; 1] *)
```

: {z: int list | z = [0; 1]}

Challenge

```
let h = handler
| return x -> x
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

$\{z: \text{int list} \mid z = [0]\}$

$\{z: \text{int list} \mid z = []\}$

```
with h handle
  (Tick (); Tock ()) : {z: int list | z = [1; 0]}
(* ==> [1; 0] *)
```

```
with h handle
  (Tock (); Tick ()) : {z: int list | z = [0; 1]}
(* ==> [0; 1] *)
```

The precise types depend on **what effects** occur in **what order**

Challenge

```
let h = handler
| return x -> x
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

$\{z: \text{int list} \mid z = []\}$

$\{z: \text{int list} \mid z = [1]\}$

The precise types depend on
what effects occur in **what order**

```
with h handle
  (Tick (); Tock ())
(* ==> [1; 0] *)
```

$: \{z: \text{int list} \mid z = [1; 0]\}$

```
with h handle
  (Tock (); Tick ())
(* ==> [0; 1] *)
```

$: \{z: \text{int list} \mid z = [0; 1]\}$

Challenge

```
let h = handler  
| return x -> x  
| Decide (), k -> k true - k false
```

```
with h handle  
  (if Decide () then n1 else n2) : {z: int | z = n1 - n2}  
  (* ==> n1 - n2 *)
```

The precise type depends on
which branch returns **what value**

Challenge

```
let h = handler  
| return x -> x  
| Decide (), k -> k true - k false
```

$\{z: \text{int} \mid z = n_2\}$

$\{z: \text{int} \mid z = n_1\}$

```
with h handle  
  (if Decide () then n1 else n2)  
(* ==> n1 - n2 *)
```

$: \{z: \text{int} \mid z = n_1 - n_2\}$

The precise type depends on
which branch returns **what value**

Challenge

Need to track precise types of the contexts
(i.e., answer types) of each operation call in e

??

$\Gamma \vdash \text{with } h \text{ handle } e : ??$



We adopt

Answer Type Modification

[Danvy+90; Materzok+11]

Answer Types

- Types of **delimited contexts**
 - = return types of **delimited continuations**
 - = types of **the closest outer handling constructs (delimiters)**

$\mathcal{E}[\text{with } h \text{ handle } \mathcal{F}[e]]$

evaluation context

handler-free
evaluation context

Answer type of e = type of **with h handle $\mathcal{F}[\]$**

$\mathcal{F} ::= [\] \mid \text{let } x = \mathcal{F} \text{ in } e$

$\mathcal{E} ::= [\] \mid \text{let } x = \mathcal{E} \text{ in } e \mid \text{with } h \text{ handle } \mathcal{E}$

Answer Types in Ordinary Type Systems

value types $T ::= B \mid T \rightarrow C$

computation types $C ::= \Sigma \triangleright T$

signatures $\Sigma ::= \{\text{Op}_i : T_{ai} \twoheadrightarrow T_{bi}\}_i$

answer type

$$\frac{\Gamma \vdash e : \{\text{Op}_i : T_{ai} \twoheadrightarrow T_{bi}\}_i \triangleright T_0 \quad \Gamma, x : T_0 \vdash e_r : \mathbf{C} \quad (\Gamma, x : T_{ai}, k : T_{bi} \rightarrow \mathbf{C} \vdash e_i : \mathbf{C})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : \mathbf{C}}$$

$$\frac{\Sigma \ni \text{Op} : T_a \twoheadrightarrow T_b \quad \Gamma \vdash v : T_a}{\Gamma \vdash \text{Op } v : \Sigma \triangleright T_b}$$

$$\boxed{\Gamma \vdash e : C}$$

Answer Types in Ordinary Type Systems

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()
```

int list

int list

int list

unit $\rightarrow$ int list

$\vdash$ with h handle (Tick();Tock()) : **int list**

Answer Type Modification

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()
```

```
with h handle (Tick ()); Tock ())
```

Answer Type Modification

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

unit $\rightarrow$ {z: int list | z = []}

with h handle () returns []

```
with h handle (Tick (); Tock ())
→ 1 :: with h handle (()); Tock ()
→ 1 :: with h handle (Tock ())
→ 1 :: 0 :: with h handle ( )
→ 1 :: 0 :: []
```

Answer Type Modification

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

unit $\rightarrow \{z: \text{int list} \mid z = []\}$

$\{z: \text{int list} \mid z = [0]\}$

with h handle () returns []

1 :: [] takes [0]

```
with h handle (Tick (); Tock ())
→ 1 :: with h handle (()); Tock ()
→ 1 :: with h handle (Tock ())
→ 1 :: 0 :: with h handle ( )
→ 1 :: 0 :: []
```

Answer Type Modification

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

Initial answer type

Final answer type

unit $\rightarrow$ {z: int list | z = []}

{z: int list | z = [0]}

Answer type modification (ATM)

Answer refinement modification (ARM)

```
with h handle (Tick (); Tock ())
→ 1 :: with h handle (()); Tock ()
→ 1 :: with h handle (Tock ())
→ 1 :: 0 :: with h handle ()
→ 1 :: 0 :: []
```

Answer Type Modification

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

unit → {z: int list | z = [0]}

with h handle (Tick (); Tock ())

→ 1 :: with h handle ((); Tock ())

→ 1 :: with h handle (Tock ())

→ 1 :: 0 :: with h handle ()

→ 1 :: 0 :: []

Answer Type Modification

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

unit → {z: int list | z = [0]}

{z: int list | z = [1; 0]}

with h handle (Tick (); Tock ())

→ 1 :: with h handle ((); Tock ())

→ 1 :: with h handle (Tock ())

→ 1 :: 0 :: with h handle ()

→ 1 :: 0 :: []

Type Syntax

value types

$T ::= \{x: B \mid \phi\} \mid T \rightarrow C$

computation types

$C ::= \Sigma \triangleright T / \textcolor{brown}{S}$

signatures

$\Sigma ::= \{\text{Op}_i: T_{ai} \twoheadrightarrow T_{bi} / \textcolor{brown}{C}_{1i} \Rightarrow \textcolor{blue}{C}_{2i}\}_i$

control effects

$\textcolor{brown}{S} ::= \square \mid \textcolor{brown}{C}_1 \Rightarrow \textcolor{blue}{C}_2$

The answer type does not change

The initial answer type $\textcolor{brown}{C}_1$ is modified to the final answer type $\textcolor{blue}{C}_2$

Typing Rules

- **Example** $\Sigma = \{ \text{Tick: unit} \rightarrow \text{unit} / \{z: \text{int list} \mid z = [0]\} \Rightarrow \{z: \text{int list} \mid z = [1; 0]\},$
 $\text{Tock: unit} \rightarrow \text{unit} / \{z: \text{int list} \mid z = []\} \Rightarrow \{z: \text{int list} \mid z = [0]\} \}$

```
let h = handler
| return x -> []
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

with h handle (

$$\frac{\Gamma \vdash e_1 : \Sigma \triangleright \text{unit} / \mathbf{C} \Rightarrow \mathbf{C}_F \quad \Gamma \vdash e_2 : \Sigma \triangleright T / \mathbf{C}_I \Rightarrow \mathbf{C}}{\Gamma \vdash e_1; e_2 : \Sigma \triangleright T / \mathbf{C}_I \Rightarrow \mathbf{C}_F}$$

$\text{Tick } () ; : \Sigma \triangleright \text{unit} / \{z: \text{int list} \mid z = [0]\} \Rightarrow \{z: \text{int list} \mid z = [1; 0]\}$

$\text{Tock } () : \Sigma \triangleright \text{unit} / \{z: \text{int list} \mid z = []\} \Rightarrow \{z: \text{int list} \mid z = [0]\}$

)

Typing Rules

- Example**

$$\Sigma = \{ \text{Tick: unit} \rightarrow \text{unit} / \{z: \text{int list} \mid z = [0]\} \Rightarrow \{z: \text{int list} \mid z = [1; 0]\}, \\ \text{Tock: unit} \rightarrow \text{unit} / \{z: \text{int list} \mid z = []\} \Rightarrow \{z: \text{int list} \mid z = [0]\} \}$$

let h = handler

```
| return x -> [] : {z: int list | z = []}
| Tick (), k -> 1 :: k ()
| Tock (), k -> 0 :: k ()
```

with h handle (

$$\left(\begin{array}{l} \text{Tick } () \\ \text{Tock } () \end{array} \right) : \Sigma \triangleright \text{unit} / \{z: \text{int list} \mid z = []\} \Rightarrow \{z: \text{int list} \mid z = [1; 0]\}$$

)

$$\frac{\Gamma \vdash e_1 : \Sigma \triangleright \text{unit} / \mathcal{C} \Rightarrow \mathcal{C}_F \quad \Gamma \vdash e_2 : \Sigma \triangleright T / \mathcal{C}_I \Rightarrow \mathcal{C}}{\Gamma \vdash e_1; e_2 : \Sigma \triangleright T / \mathcal{C}_I \Rightarrow \mathcal{C}_F}$$

Typing Rules

- **Example** $\Sigma = \{ \text{Tick: unit} \rightarrow \text{unit} / \{z: \text{int list} \mid z = [0]\} \Rightarrow \{z: \text{int list} \mid z = [1; 0]\},$
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```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()
```

```
(
  with h handle (
    Tick ();
    Tock ()
  )
) : {z: int list | z = [1; 0]}
```

Typing Rules

$$\frac{\Gamma \vdash e : \{\text{Op}_i: T_{ai} \rightarrow T_{bi} / \mathcal{C}_{1i} \Rightarrow \mathcal{C}_{2i}\}_i \triangleright T_0 / \mathcal{C}_1 \Rightarrow \mathcal{C}_2 \quad \Gamma, x: T_0 \vdash e_r : \mathcal{C}_1 \quad (\Gamma, x: T_{ai}, k: T_{bi} \rightarrow \mathcal{C}_{1i} \vdash e_i : \mathcal{C}_{2i})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : \mathcal{C}_2}$$

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$$\boxed{\Gamma \vdash e : \mathcal{C}}$$

Typing Rules

$$\frac{\Gamma \vdash e : \{\text{Op}_i: T_{ai} \rightarrow T_{bi} / C_{1i} \Rightarrow C_{2i}\}_i \triangleright T_0 / C_1 \Rightarrow C_2 \quad \Gamma, x: T_0 \vdash e_r : C_1 \quad (\Gamma, x: T_{ai}, k: T_{bi} \rightarrow C_{1i} \vdash e_i : C_{2i})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : C_2}$$

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$$\boxed{\Gamma \vdash e : C}$$

Typing Rules

$$\frac{\Gamma \vdash e : \{\text{Op}_i: T_{ai} \rightarrow T_{bi} / C_{1i} \Rightarrow C_{2i}\}_i \triangleright T_0 / \textcolor{brown}{C}_1 \Rightarrow \textcolor{blue}{C}_2 \quad \Gamma, x: T_0 \vdash e_r : \textcolor{brown}{C}_1 \quad (\Gamma, x: T_{ai}, k: T_{bi} \rightarrow C_{1i} \vdash e_i : C_{2i})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : \textcolor{blue}{C}_2}$$

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$$\boxed{\Gamma \vdash e : C}$$

Extension 1: Predicate Polymorphism

value types $T ::= B \mid T \rightarrow C$

computation types $C ::= \Sigma \triangleright T / S$

signatures $\Sigma ::= \{\text{Op}_i: \forall X: \bar{B}. T_{ai} \twoheadrightarrow T_{bi} / C_{1i} \Rightarrow C_{2i}\}_i$

control effects $S ::= \square \mid C_1 \Rightarrow C_2$

$$\Gamma \vdash e : \{\text{Op}_i: \forall X: \bar{B}. T_{ai} \twoheadrightarrow T_{bi} / C_{1i} \Rightarrow C_{2i}\}_i \triangleright T_0 / C_1 \Rightarrow C_2$$
$$\frac{\Gamma, x: T_0 \vdash e_r : C_1 \quad (\Gamma, X: \bar{B}, x: T_{ai}, k: T_{bi} \rightarrow C_{1i} \vdash e_i : C_{2i})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : C_2}$$
$$\Sigma \ni \text{Op}: \forall X: \bar{B}. T_a \twoheadrightarrow T_b / C_1 \Rightarrow C_2 \quad \Gamma \vdash v : T_a \quad \Gamma \vdash \text{Pred} : \bar{B}$$
$$\Gamma \vdash \text{Op } v : \Sigma \triangleright (T_b / C_1 \Rightarrow C_2) [\text{Pred}/X]$$

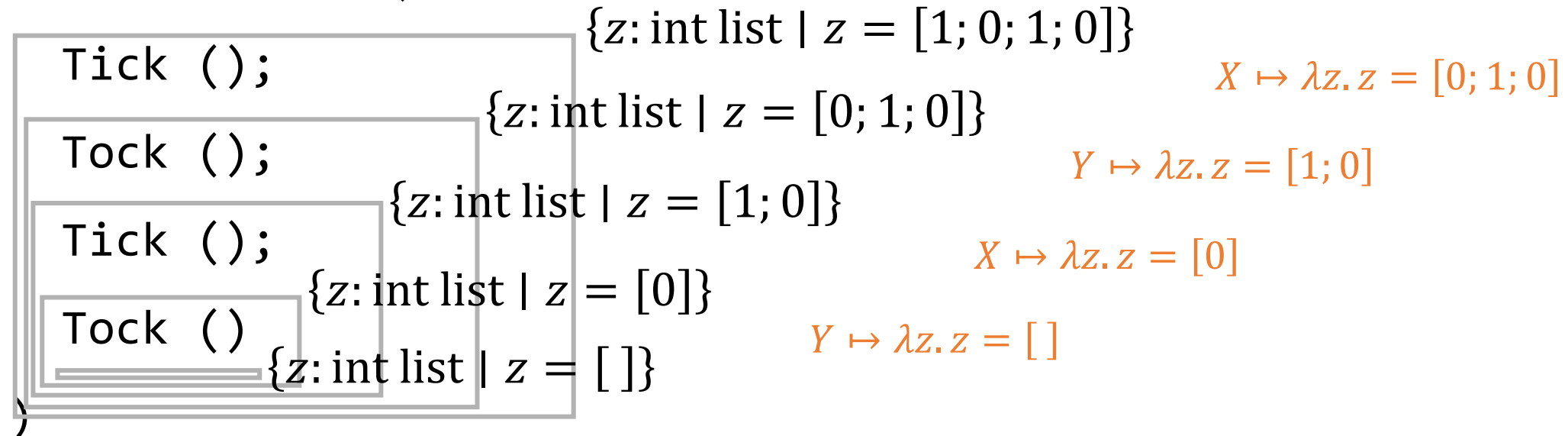
$\Gamma \vdash e : C$

Extension 1: Predicate Polymorphism

● Example

```
let h = handler
  | return x -> []
  | Tick (), k -> 1 :: k ()
  | Tock (), k -> 0 :: k ()
```

with h handle (



Extension 2: Dependent Types for Continuations

value types $T ::= B \mid T \rightarrow C$

computation types $C ::= \Sigma \triangleright T / S$

signatures $\Sigma ::= \{\text{Op}_i: T_{ai} \twoheadrightarrow T_{bi} / \textcolor{brown}{y}. C_{1i} \Rightarrow C_{2i}\}_i$

control effects $S ::= \square \mid \textcolor{brown}{y}. C_1 \Rightarrow C_2$

$$\frac{\Gamma \vdash e : \{\text{Op}_i: T_{ai} \twoheadrightarrow T_{bi} / \textcolor{brown}{y}. C_{1i} \Rightarrow C_{2i}\}_i \triangleright T_0 / C_1 \Rightarrow C_2 \quad \Gamma, x: T_0 \vdash e_r : C_1 \quad (\Gamma, x: T_{ai}, k: (\textcolor{brown}{y}: T_{bi}) \rightarrow C_{1i} \vdash e_i : C_{2i})_i}{\Gamma \vdash \mathbf{with} \{x \mapsto e_r, (\text{Op}_i x, k \mapsto e_i)_i\} \mathbf{handle} e : C_2}$$

$$\frac{\Sigma \ni \text{Op}: T_a \twoheadrightarrow T_b / \textcolor{brown}{y}. C_1 \Rightarrow C_2 \quad \Gamma \vdash v : T_a}{\Gamma \vdash \text{Op } v : \Sigma \triangleright (T_b / \textcolor{brown}{y}. C_1 \Rightarrow C_2)}$$

$$\boxed{\Gamma \vdash e : C}$$

Extension 2: Dependent Types for Continuations

● Example

```
let h = handler
| return x -> x
| Decide (), k -> k true - k false
```

$(b: \text{bool}) \rightarrow \{z: \text{int} \mid b \Rightarrow z = n_1 \wedge \neg b \Rightarrow z = n_2\}$

$\Sigma = \{\text{Decide: unit} \twoheadrightarrow \text{bool} / b. \{z: \text{int} \mid b \Rightarrow z = n_1 \wedge \neg b \Rightarrow z = n_2\} \Rightarrow \{z: \text{int} \mid z = n_1 - n_2\}\}$

with h handle (

let b = Decide () in

if b then n_1 else n_2

$\{z: \text{int} \mid z = n_1 - n_2\}$

$\{z: \text{int} \mid b \Rightarrow z = n_1 \wedge \neg b \Rightarrow z = n_2\}$

Automatic Type Inference via CHC Solving

1. Obtain an ML-typed AST using OCaml's compiler library
2. Infer refinement-free operation signatures and control effects
3. Generate refinement constraints for the program and its specification as Constrained Horn Clauses (CHCs) [Unno and Kobayashi '09]
4. Solve CHCs to check if the program satisfies the specification

The POPL'24 Paper also Includes:

- A proof of the type soundness
- Implementation in **RCaml**
 - On top of OCaml 5.0
 - Experiments on 50+ examples
- Another way of verification via CPS transformation
 - Removal of handlers + verification with existing refinement type systems
 - Bidirectionally type-preserving CPS transformation
 - Needs type annotations on source programs

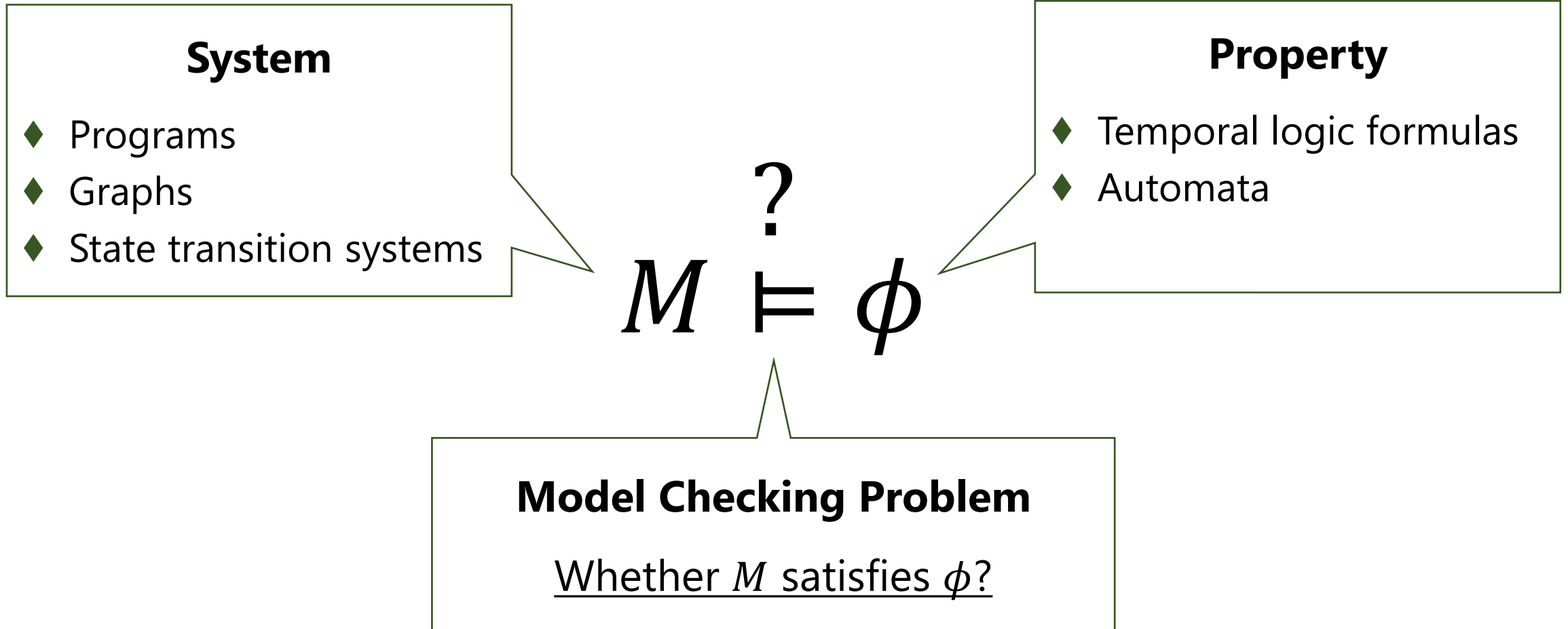


<https://github.com/hiroshi-unno/coar>

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Model Checking



Higher-Order Model Checking (HOMC)

[Ong, LICS'06; Kobayashi, JACM'13]

System

HO programs yielding trees

- ◆ HO recursion schemes (tree grammars with HO funcs)
- ◆ PCF terms with finite ground types (generating Böhm trees)

Property

Predicates over trees

- ◆ MSO formulas
- ◆ Modal μ -calculus formulas
- ◆ Alternating parity tree automata

$$M \stackrel{?}{\models} \phi$$

HOMC Problem

Whether the tree generated by M satisfies ϕ ?

- ◆ E.g. assertion checking, (non-)termination verification, and general branching-time temporal safety and liveness verification problems

Higher-Order Model Checking (HOMC)

[Ong, LICS'06; Kobayashi, JACM'13]

System

HO programs yielding trees

- ◆ HO recursion schemes (tree grammars with HO funcs)
- ◆ PCF terms with finite ground types (generating Böhm trees)

Property

Predicates over trees

- ◆ MSO formulas
- ◆ Modal μ -calculus formulas
- ◆ Alternating parity tree automata

$M \stackrel{?}{\models} \phi$

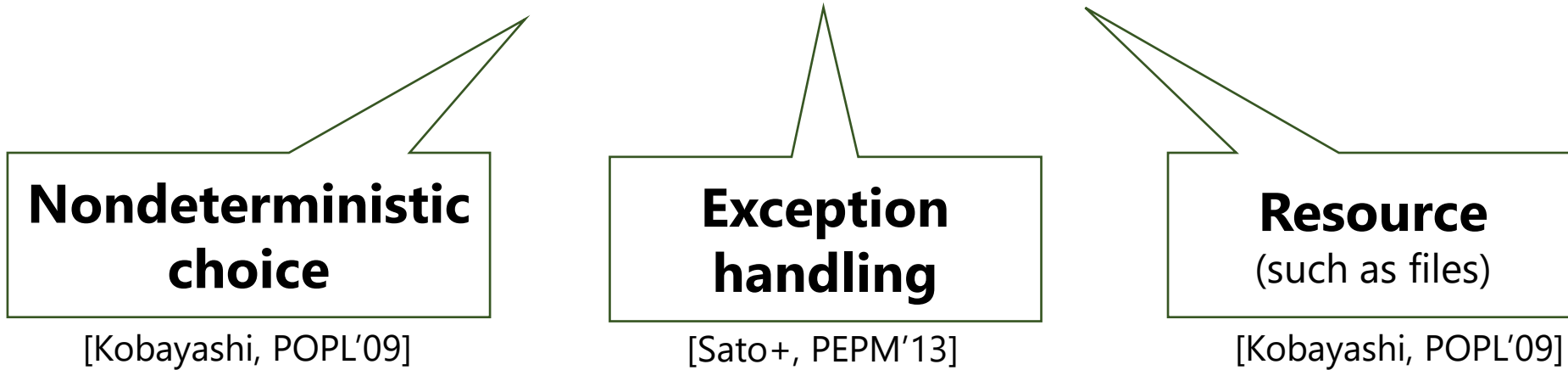
👉 Data domains need to be finite

HOMC Problem is Decidable 😊

Whether the tree generated by M satisfies ϕ ?

- ◆ E.g. assertion checking, (non-)termination verification, and general branching-time temporal safety and liveness verification problems

HOMC for Effects



What about other effects?

E.g., mutable store, I/O, backtracking, coroutines, etc.

Can express global store, I/O,
nondeterministic choice, etc.

HOMC

+

Can express exceptions,
local store, backtracking, etc.
by using **delimited continuations**

Algebraic Effects & Effect Handlers

[Dal Lago and Ghyselen, POPL'24]

Can express global store, I/O,
nondeterministic choice, etc.

HOMC

+

Can express exceptions,
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Algebraic Effects & Effect Handlers

[Dal Lago and Ghyselen, POPL'24]

is

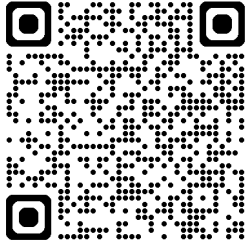
Undecidable

Idea: encoding natural numbers
through delimited continuations

Is there a useful fragment
where HOMC is decidable?



Our Contributions



- A new class of HO programs with effect handlers where
 - 😊 **HOMC is decidable**
 - 😊 **Effect handlers are expressive enough to implement various effects**

Key idea : restrict the use of delimited continuations through an Answer-Type Modification (ATM) type system [Danvy+90; Materzok+11]

- A CPS-transformation to obtain terms in a **decidable** variant of PCF with finite ground types and effect operations **without handlers**
 - Crucial both theoretically and practically
- Implementation of a model checker **EffCaml** for the new class

- Higher-order functions
- + General recursion
- + Finite data domains (like Bool)

Effect Handlers

[Dal Lago and Ghyselen, POPL'24]

- Target language: HEPCF
 - HEPCF = A variant of PCF + **Effect Operations** + **Handlers**

Terms $M ::= \dots \mid \text{op}(V, x. M) \mid \text{with } H \text{ handle } M$

Handlers $H ::= \{ \text{return } x \rightarrow M \} \uplus \{ \text{op}_i(x_i, k_i) \rightarrow M_i \}_i$

$\text{let } x = \text{op}(V, y. M) \text{ in } M_2 \longrightarrow \text{op}(V, y. \text{let } x = M \text{ in } M_2)$

$\text{with } H \text{ handle } \text{op}(V, y. M) \longrightarrow M'[x \mapsto V][k \mapsto \lambda y. \text{with } H \text{ handle } M]$
(if $\text{op}(x, k) \rightarrow M' \in H$)

M' can access to the delimited continuation via k

HOMC for Effect Handlers [Dal Lago and Ghyselen, POPL'24]

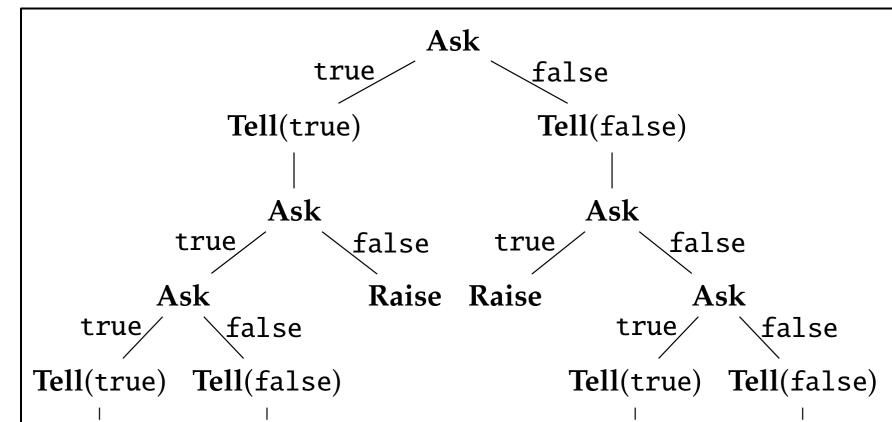
- Target language: HEPCF
 - HEPCF = A variant of PCF + **Effect Operations + Handlers**
 - Equipped with effect tree semantics
 - The generated trees comprise **unhandled** operations as well as arguments and returns values of the operations

HEPCF term

```
let rec f g =  
  let b1 = ask x in  
  if g b1 then ()  
  else  
    let b2 = ask x in  
    if b1 = b2 then f g  
    else raise ()  
f (fun b -> tell b; false)
```

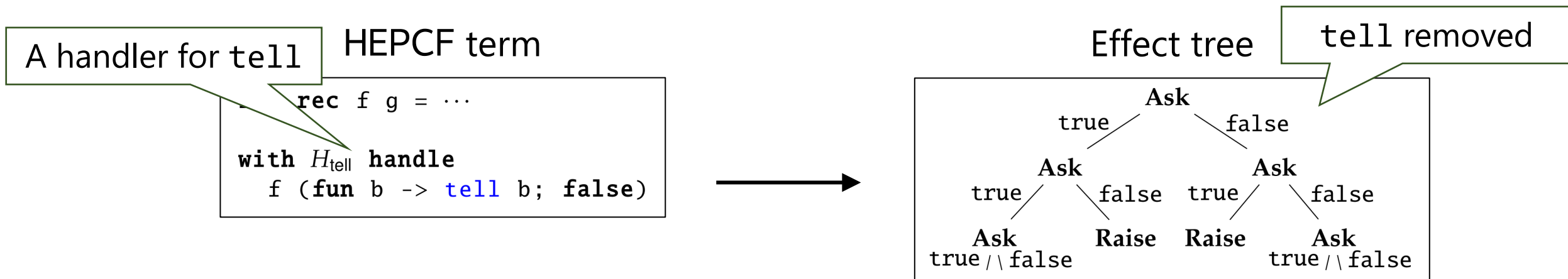


Effect tree



HOMC for Effect Handlers [Dal Lago and Ghyselen, POPL'24]

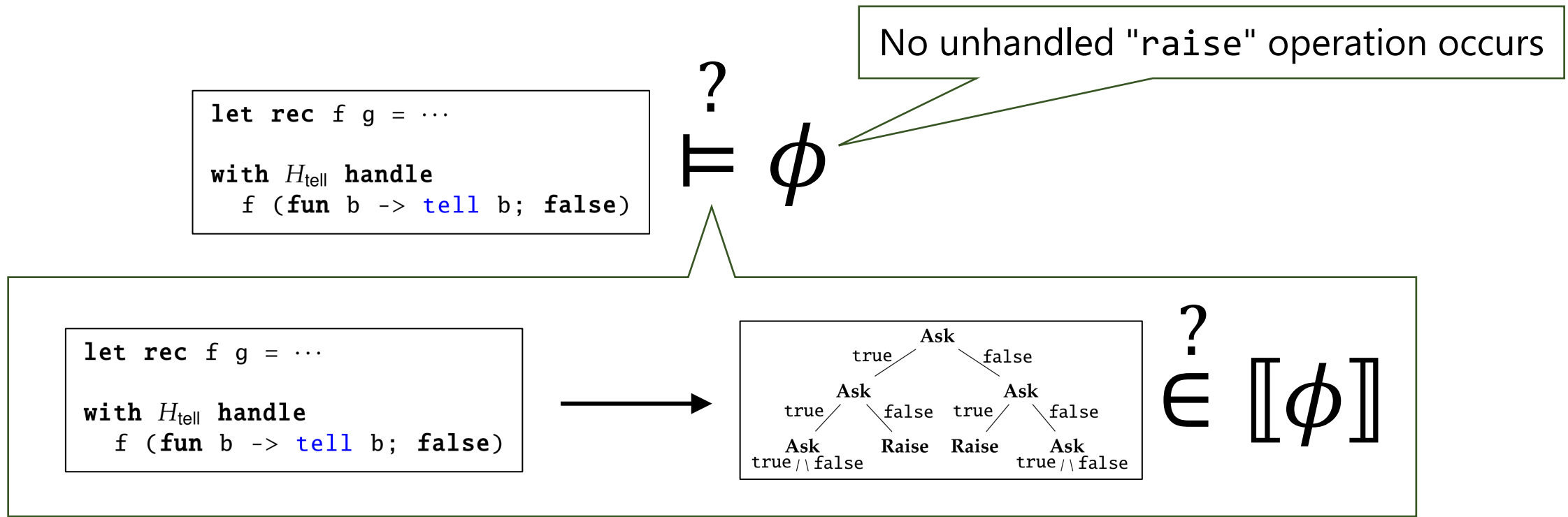
- Target language: HEPCF
 - HEPCF = A variant of PCF + **Effect Operations + Handlers**
 - Equipped with effect tree semantics
 - The generated trees comprise **unhandled** operations as well as arguments and returns values of the operations
 - Handlers "fold" over effect trees



HOMC for Effect Handlers

[Dal Lago and Ghyselen, POPL'24]

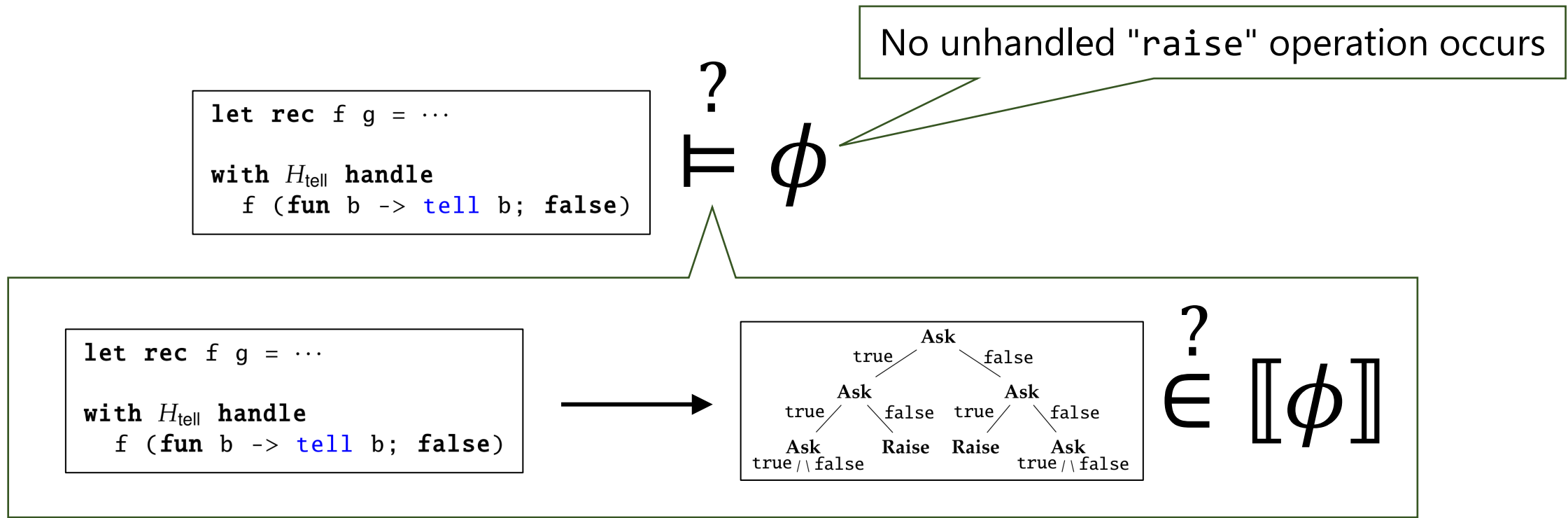
- Model checking



HOMC for Effect Handlers

Reminder: infinite data domains makes the HOMC undecidable

- Model checking is **undecidable** 😞 for MSO formulas ϕ because **effect handlers can encode natural numbers**



Encoding of Natural Numbers [Dal Lago and Ghyselen, POPL'24]

n calls to operation `succ`

$$\llbracket n \rrbracket = \lambda x. \text{succ}(); \dots; \text{succ}(); x$$

$$\begin{aligned} \llbracket \text{case}(V; 0 \mapsto M_0; \text{succ}(x) \mapsto M_1) \rrbracket &= \text{with } H \text{ handle } \llbracket V \rrbracket () \\ \text{where } H &= \{\text{return } _ \rightarrow \llbracket M_0 \rrbracket, \text{succ}(_, x) \rightarrow \llbracket M_1 \rrbracket\} \end{aligned}$$

(Here shallow effect handlers are assumed, but
it is possible to adapt the encoding to deep handlers)

[Hillerström and Lindley, APLAS'18]

- Encoding of basic arithmetic operations

$$\begin{aligned} \llbracket V - n \rrbracket &= \text{with } H \text{ handle } (\dots (\text{with } H \text{ handle } \llbracket V \rrbracket ()) \dots) \\ \text{where } H &= \{\text{return } _ \rightarrow \llbracket 0 \rrbracket, \text{succ}(_, x) \rightarrow x()\} \end{aligned}$$

Key Idea to Prevent the Nat Encoding

Bounding # of simultaneously active effect handlers

Formal Statement

For any term e to be model checked,

$$\exists n. \forall e', H_1, \dots, H_n. e \not\rightarrow \text{with } H_1 \text{ handle } (\dots (\text{with } H_n \text{ handle } e') \dots)$$

 **Why does it prevent the encoding?** $\llbracket V - n \rrbracket = \text{with } H \text{ handle } (\dots (\text{with } H \text{ handle } \llbracket V \rrbracket ()) \dots)$

Predecessor is implemented by effect handlers

- Bounding # of simultaneously active effect handlers results in bounding # of applications of the predecessor
- The restriction bounds the range of accessible natural numbers

Approach to Implementing the Restriction

Types of delimited continuations

- Use a type system with ***answer types*** [Danvy+90; Materzok+11]
 - Essentially the same as the ATM type system in [Kawamata+ POPL'24] without polymorphism, dependency, and refinements
 - Answer types reveal # of delimited continuations necessary to evaluate terms
 - **# of delimited continuations = # of effect handlers that can be active**
 - Bounding answer types enables bounding # of simul. active effect handlers

Types

Value types	$T ::= B \mid T \rightarrow C$
Computation types	$C ::= \Sigma \triangleright T / A^{\text{ini}} \Rightarrow A^{\text{fin}}$
Operation signatures	$\Sigma ::= \{\sigma_i : T_i^{\text{par}} \rightsquigarrow T_i^{\text{ari}} / A_i^{\text{ini}} \Rightarrow A_i^{\text{fin}}\}^{1 \leq i \leq n}$
Answer types	$A ::= T \mid C$

Initial answer type: the return type of the delimited cont. enclosing terms

Final answer type: the argument type of the meta-continuation

Value types	$T ::= \text{...} \mid T \rightarrow C$
Computation types	$C ::= \Sigma \triangleright T / \boxed{A^{\text{ini}}} \Rightarrow \boxed{A^{\text{fin}}}$
Operation signatures	$\Sigma ::= \{\sigma_i : T_i^{\text{par}} \rightsquigarrow T_i^{\text{ari}} / A_i^{\text{ini}} \Rightarrow A_i^{\text{fin}}\}^{1 \leq i \leq n}$
Answer types	$A ::= T \mid C$

- CPS interpretation of computation types (except for Σ)

$$\llbracket T / A_1 \Rightarrow A_2 \rrbracket_{\text{CPS}} = (\llbracket T \rrbracket_{\text{CPS}} \rightarrow \llbracket A_1 \rrbracket_{\text{CPS}}) \rightarrow \llbracket A_2 \rrbracket_{\text{CPS}}$$

- For a computation type $C = T_1 / A_1 \Rightarrow (T_2 / A_2 \Rightarrow (\dots \Rightarrow (T_n / A_n \Rightarrow T) \dots))$

$$\begin{aligned} \llbracket C \rrbracket_{\text{CPS}} = & (\llbracket T_1 \rrbracket_{\text{CPS}} \rightarrow \llbracket A_1 \rrbracket_{\text{CPS}}) \rightarrow \\ & (\llbracket T_2 \rrbracket_{\text{CPS}} \rightarrow \llbracket A_2 \rrbracket_{\text{CPS}}) \rightarrow \dots \rightarrow \\ & (\llbracket T_n \rrbracket_{\text{CPS}} \rightarrow \llbracket A_n \rrbracket_{\text{CPS}}) \rightarrow \llbracket T \rrbracket_{\text{CPS}} \end{aligned}$$

Results

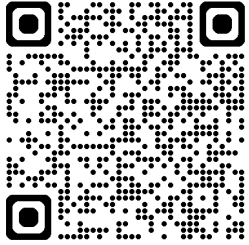
😊 The model checking of HEPCF terms well-typed in our type system is **decidable**

Proof strategy: Reducing the HOMC for effect handlers to
the (decidable) HOMC for algebraic effects
via a semantics-preserving CPS transformation

😊 Our type system accepts effect handlers for exceptions, local store, backtracking, etc.

Because it restricts the use of effect handlers, not themselves

Implementation: EffCaml



- A model checker for a subset of OCaml 5 with effect handlers
 1. Inference of ML types, operation signatures, and control effects
 2. CPS-transformation to eliminate effect handlers
 3. Apply HOMC tool HorSat2 [Kobayashi 2016] to the result of 2.
- Preliminary experiment results

File name	Lines of code	Safe/Unsafe	Result correct?	Time (sec.)
file.ml	53	Safe	Yes	0.005
file_unsafe.ml	52	Unsafe	Yes	0.004
immutable_false.ml	42	Safe	Yes	0.004
immutable_mutable_set_not_b_false.ml	64	Safe	Yes	0.004
immutable_set_not_b_false.ml	44	Safe	Yes	0.004
immutable_true.ml	42	Safe	Yes	0.004
mutable_false.ml	43	Safe	Yes	0.004
mutable_immutable_set_not_b_false.ml	63	Unsafe	Yes	0.004
mutable_set_not_b_false.ml	45	Unsafe	Yes	0.005
mutable_true.ml	43	Safe	Yes	0.003

Conclusions

Automated precise verification of effect-handling programs

- ◇ By an ATM refinement type system that precisely tracks answer refinement types

Decidable HOMC of effect-handling programs

- ◇ By an ATM type system that bounds # of simultaneously active effect handlers

Takeaway: Answer types are effective in reasoning about effect-handling programs

- Other application: type-based temporal verification [Sekiyama & Unno, POPL'23]

Ongoing and Future Work

- Support other variants of effect handlers
 - E.g., shallow and lexical handlers
- Extend ATM type systems with varying levels of polymorphism to balance modularity and precision of verification
 - Effect polymorphism
 - specifying a part of an operation signature as a parameter
 - Control effect polymorphism
 - Computation and value type polymorphism
- Enhance **RCaml** and **EffCaml** to be more scalable and to support more language features and specifications
 - Combination with other effects such as parallelism and temporal effects